# Bayesian adaptive Lasso Tobit regression with a practical application 

A thesis submitted for the degree of<br>MASTER OF STATSTICAL SCIENCE<br>By<br>Haider Kadhim Abbas Hilali

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## Supervisor's recommendation

I certify that the thesis (Bayesian adaptive Lasso Tobit regression with a practical application) has been under my supervision in the Department of Statistics/College of Administration \& Economics/University of Al_Qadisiyah it is a part of the requirements for a master's degree in statistics.


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We are the head and members of the defense committee certify that we have been looked at the thesis entitled (Bayesian adaptive Lasso Tobit regression with a practical application) and we have debated the student (Haider Kadhim Abbas Hilali). As a result, the student has defended his thesis and all its content. So that we have found the thesis is worthy to be accepted to award the degree of Master in statistics sciences.


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## DEDICATION

This thesis is dedicated to my beloved family and my dear wife and sons for their continuous supports and always being with me


#### Abstract

The process of the variable selection refers to the category of problems where one attempt to determine the best subset of the pertinent variables, which can be used to obtain accurate adjustments to the results of a given response variable. Often, when the number of variables is too large, it is difficult to identify important and influential variables on the response variable. For this reason, the variable selection (VS) characteristic was considered very important in the data analysis. Regularization techniques is one fabulous way that has proven effectively for dealing with high dimensional data.

In previous years, statisticians have made great efforts in developing procedures of regularization to solve problems of VS. These procedures auto facilitate for VS by setting specific coefficients to zero and shrinking the coefficients estimates, and provide advantageous estimates even if the model contains a large number of highly correlated variables. Although the regularizations approaches have developed in recent years, these procedures can still be improved.

In this thesis, we have proposed new techniques for model selection in Tobit regression. These techniques are Bayesian Lasso and Bayesian adaptive Lasso in Tobit regression (BLTR, and BALTR). These techniques have many features that give good estimation and VS. Specifically, we have introduced a new hierarchal model for each technique. Then, new Gibbs sampler methods are introduced. We also extended the new approaches by adding the ridge parameter inside the variance-covariance matrix to avoid the singularity in case of multicollinearity or


in case the number of predictors greater than the number of observations. A comparison was made with other existing techniques by applying the simulation examples and real data. It is worth mentioning, that the obtained results are promising and encouraging, giving better results compared to the existing methods.

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## CHAPTER ONE

## 1. Introduction:

Linear statistical models are widely used in biological, agricultural, physical and social sciences, biology, as well as in economics and engineering. They are useful in both planning stages of research and analysis of the resulting data. We are aware of that regression analysis is one of the statistical procedures that illustrate the relationships between explanatory variables and the dependent variable (outcome). When the explanatory variables values are known, then the regression analysis assistance us to predict the values of the outcome variable. Variable selection is a difficult and important problem that is an important goal for many types of statistical modelling. The difficulty of this problem is increased in actual applications when a true model may not exist. Given a dataset, you can fit many models.

In addition, in order to reach accurate results from the studied event, the selected model must correspond the available data as best as possible, and the proposed regression process for the data in question will lead to results that are close to real. However, when the independent variables are too large, or the number of observations is less than the number of variables, then it is very difficult to distinguish the independent variables that are important and influential in describing the Tobit regression model, which leads to the instability and overfitting of the model, consequently the model lacks the validity of the prediction. To get rid of these problems, statisticians resorted to the mechanism of selecting the important and influential variables, while at the same time eliminating as much as possible from the explanatory variables that are not important, this procedure is

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known variable selection (VS). Although all VS procedures have evolved in recent years in linear regression, these procedures can still be improved.

In generals, the main objective of this thesis is to present several Bayesian regularization approaches in the framework of Tobit regression. These approaches are Bayesian Lasso and Bayesian adaptive Lasso in Tobit regression (BLTR, and BALTR). These approaches have many features that give a good estimation and get rid of all problems by variable selection.

## 2. Literature Review:

In many applications, the observations are partially constrained with the dependent variable and not constrained in the other part. This data is called censored data. The application of the conventional regression with this type of data will lead to biased parameters on the one hand, and inconsistent on the other hand. Therefore, it is necessary to determine a regression process that is proportional to this data. Such a model was first proposed in a great exertion via Tobin (1958). Tobin analyzed the dependent variables of the regression model that cannot be negative. Consequently, the Tobit regression process is appropriate to this data, it is elucidating the relationship among the non-negative dependent outcome variable and the independent explanatory variables. The function of Tobit regression is a mixed function, it deals with two-part data, each part of the outcome variable data will take a given distribution. The dependent variable data that equal to zero will take the cumulative distribution function of the normal distribution, and the data is larger than zero will take probability density function.

Between 1958 "when Tobin's articles appeared" and 1970, the Tobit model was used infrequently in econometric applications. At the same time, many Tobit

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models and several evaluation procedures have been suggested for these models. Additionally, estimation procedures are now many and varied, but it is hard for statisticians to follow all current models and estimation procedures. The Tobit regression has been used in many studies, and the statisticians have applied this regression in many packages of different statistical language programs, such as the Tobit function in AER package (Kleiber et al., 2017), and MCMCtobit function in MCMCpack package (Martin et al., 2018) . The general formula of Tobit regression is

$$
y_{i}=\left\{\begin{array}{cr}
y_{i}^{*} & y_{i}^{*}>0 \\
0 & \text { otherwise } \leq 0
\end{array}\right.
$$

where $y_{i}$ denote the outcome variable of interest for $i=1, \ldots, n$. Here, $y_{i}^{*}$ denote a latent response variable as follows

$$
\begin{equation*}
y_{i}^{*}=x_{i}^{\prime} \boldsymbol{\beta}+\varepsilon_{i}, \tag{1.1}
\end{equation*}
$$

where $x_{i}^{\prime}$ is the $1 \times k$ vector denoting the $i$ th row of the $n \times k$ matrix of predictors $\boldsymbol{X}$, and the vector of predictors $\boldsymbol{\beta}$ is

$$
\boldsymbol{\beta}=\left(\beta_{0}, \beta_{1}, \cdots, \beta_{k}\right)^{\prime},
$$

and $\varepsilon_{i}$ is the error term, $p\left(\varepsilon_{i}\right)=\operatorname{Normal}\left(0, \sigma^{2}\right), k$ is a number of independent variables, and $n$ is the number of observations.

However, previous attempts of applying Tobit regression in diverse applications, VS are used in multiple fields. This performance opens the doors for applying this technique in several topics that enable statisticians to analyze the data. Especially, when the data has a wide array of variables. Therewith, occasionally the number of explanatory variables is too large. It is then difficult to know which variables are really important, which are the noise variables. Additionally, to the emergence of a number of problems, when we use some independent variables that are not important in describing the Tobit regression, and this leads to a regression model

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that will be unstable and weak in terms of prediction. The mechanism of VS is to improve the model prediction, providing faster and lower cost models and a good understanding of the data.

If a model is to be used for prediction, time and fatigue can be saved by measuring only necessary predictors. Frequent predictions will add noise to the estimation of other levels of interests and also leads to the loss of certain degrees of freedom. The selection of predictors among the several potential ones to be included in a model is one of the prime challenges in regression analysis. Therefore, VS procedure is very important in Tobit regression for several reasons, such as:

- Reducing the number of explanatory variables will be so beneficial for many purposes. Especially, economics and statistics.
- Besides performing VS process on a dataset, it is sometimes also useful to looks at variable importance. A high score on variable importance means that variable has a large effect on the responses and small adjustments in that variable value can lead to a large deviation in the response. Variables that score low on variable importance will mostly be removed during VS process, additionally, variables that are not removed from the model will also score high on importance.
- Creating a highly accurate precision model that gives good estimations and high predictions.

Efroymson (1960) proposed an algorithm called stepwise selection technique, considered one of the most widely known and widely used subsets selection. It is defined as an automatic process for selecting models in cases where there are a big number of possible explanatory variables. Then method is implemented mainly in regression analysis. It is a procedure that permits implements in forwards selection

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$(F S)$ and backward elimination $(B E)$ in same time, dropping or adding variables at the various steps. This procedure is created two approaches, that is $F S$ and $B E$. The $F S$ can be evaluated also by a $F$ test as follows

$$
\begin{equation*}
F_{j}^{+}=\max _{j}\left[\frac{R S S_{k}-R S S_{k+j}}{S_{k+j}^{2}}\right]>F_{i n} \tag{1.2}
\end{equation*}
$$

And the $B E$ process can be calculated by a $F$ test as follows

$$
\begin{equation*}
F_{j}^{-}=\min _{j}\left[\frac{R S S_{k-j}-R S S_{k}}{S_{k}^{2}}\right]<F_{\text {out }} . \tag{1.3}
\end{equation*}
$$

where $R S S$ is the residuals sum of squares, $k$ is the number of estimated parameters in the model, $S^{2}$ is the estimate error variance of the model, $F_{\text {in }}$ and $F_{\text {out }}$ are used as stop criterions.

Even if $k$ is less than $n$, looking at all possible models may not be the best thing to do, then the $F S$ and $B E$ approaches are not warranted to give the best model.

Mallows (1974) proposed a procedure called a Mallows $C_{k}$. This procedure named for Colin L. Mallows is applied to evaluated predictors that have been estimated via ordinary least square regression $(O L S)$. It is implemented in the model selection situation, where the number of explanatory variables is obtainable for predicting the response variable. The aim is to get the better model that contains a subset of these predictors. The small values of $C_{k}$ mean that the model is comparatively accurate. The formula of Mallows procedure is

$$
\begin{equation*}
C_{k}=\frac{R S S(k)}{S^{2}}-n+2 k, \tag{1.4}
\end{equation*}
$$

where the $R S S$ is the residuals sum of squares on a set of training data, $n$ is the samples size of data, $k$ is a number of the covariates in the model, and the $S^{2}$ is an estimation of the variance related to every response in the model. It was detecting

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that the $C_{k}$ procedure does not give equivalent values to the previous procedure, but the model with the smallest $C_{k}$ from this meaning will also be the same form with the smallest $C_{k}$ from the previous meaning. If the model is correct then $C_{k}$ will tend to be close to or smaller than $k$. Thus, a simple process of $C_{k}$ can be utilized to submit the best model. However, the $C_{k}$ procedure suffers from two major constraints, the first constraint is that $C_{k}$ approximation is only valid for large sample size, and the second constraint is that $C_{k}$ cannot deal with complex groups models as in the VS.

Akaike (1974) proposed the Akaike Information Criterion procedure a theoretical approach to information for model selection. The AIC procedure is one of the most common methods of variable selection. The value of an AIC procedure can be used to compare different models. By calculating the value of AIC for all models, the model with the lowest AIC is the best model, the formula of AIC procedure is

$$
\begin{equation*}
A I C=-2 \ln L+2 k \tag{1.5}
\end{equation*}
$$

Int terms of the residual sum of squares then $A I C$ formula is

$$
\begin{equation*}
A I C=n \ln (R S S / n)+2 k, \tag{1.6}
\end{equation*}
$$

where $L$ bis the maximum likelihood function of the model (MLE), $k$ is the number of estimated parameters in the model, $R S S$ is estimated residual of fitted model and $n$ is the sample size, with the note that the error is normal (i.i.d).

A small $R S S$ results in a lower AIC value and therefore a better model. For best subset selection the AIC offers a measure to compare models of different sizes with each other. In this way, the best model can be found. Though the AIC process suffers from two major constraints, the first constraint is that AIC relies on a weak procedure when $k$ is large, and the second constraint is that AIC is no clear penalty takes in account the number of variables.

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Schwarz (1978) proposed the Bayesian information criterion procedure (BIC), this procedure approximated the $\ln$ of the marginal density of the data, which is the density of the data unconditional on the parameters. Note that the likelihood is the density of the data conditional on the parameters. Then formula of BIC procedure is

$$
\begin{equation*}
B I C=-2 \ln L+k \ln n . \tag{1.7}
\end{equation*}
$$

The residual sum of squares ( $R S S$ ), the BIC formula is

$$
\begin{equation*}
B I C=n \ln (R S S / n)+k \ln n . \tag{1.8}
\end{equation*}
$$

Though then BIC and AIC arise from two dissimilar procedures, their explanations are alike. Exactly, a BIC procedure, such as the AIC procedure, can be clarified as a measure of model fit plus a penalty for the complexity. While $n \geq 10$ then $\ln (n)>2$ and so the penalty term in BIC is greater than the penalty term in AIC. In addition, BIC penalizes complex models more than $A I C$. The BIC usually penalizes free parameters more strongly than the AIC. However, it relies on the size of $n$ and virtual magnitude of $n$ and $k$. The BIC can be applied to compare models fitting only, then the numerical values of the response variable are identical for all estimates being compared. These compared models need not be overlapped, but that is some problems when using BIC procedure, the first problem is that BIC procedure suffers from the approximation, it is only valid for $n>k$ of parameters in the models. Additionally, the second problem is that BIC cannot handle complex groups of models as in the VS problem in high dimension data.

George and McCulloch (1993) suggested an alternative procedure for using an information criterion for model selection, this procedure is stochastic search VS (SSVS), which is feasible specifically to the Bayesian MCMC framework, is SSVS procedure. Starting with the full coefficients model and selecting the mixture prior

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distributions to removes inefficient coefficients in the regression and making them equal to zero, next that sampling the parameters from the posteriors and estimating the marginal inclusion probability (MIPs) for each coefficient using the amount of SSVS samples containing each coefficient, at end estimating the posterior model probabilities (PMPs) for each model applying the quantities of SSVS samples consumed in each model. One of the disadvantages of an SSVS procedure takes a longer time to estimate, and the model with the highest posterior model may only be visited a handful of times.

Statistical researchers and data predictors are occasionally faced with more difficulties such as a large number of independent variables or low ratio the number of observations to the number of independent variables, or because of appearing multicollinearity problems, there be many numbers of strategies for statisticians auto utilizes in transacting with highs dimensional data, as well as VS procedures, and data reduction performances. A third family of techniques that have proven beneficial in the context of high dimensional data involves alternative parameter estimation algorithms known as regularization or shrinkage techniques. There be another set of the model estimation process, which can be used in such circumstances. In a sense, these procedures regularize or adjust the imprecise and volatile estimates of the regression coefficients.

Donoho and Johnstone (1994) have first introduced the notion of VS through regularization, it was then developed by Tibshirani (1996). Although these procedures are motivated by high dimensional data, they can also be effectively applied to sparse low to moderate dimensional problems, facilitating applications in a wide range of scientific problems. The general formula model, that illustrates the concept of regularization procedures, can be written as follows

$$
\begin{equation*}
\widehat{\boldsymbol{\beta}}=\underset{\boldsymbol{\beta}}{\operatorname{argmin}}(\boldsymbol{y}-\boldsymbol{X} \boldsymbol{\beta})^{\prime}(\boldsymbol{y}-\boldsymbol{X} \boldsymbol{\beta})+F_{\lambda}(\boldsymbol{\beta}), \tag{1.9}
\end{equation*}
$$

where $F_{\lambda}($.$) is a function of the model coefficients in terms by a positive penalty$ parameter.
This parameter has an effective influence in VS, where it controls the degree of deflation applied to estimates. Regularization procedures recognize good values of $\widehat{\boldsymbol{\beta}}$ such that the at most important coefficients accept advanced values, and the minimum important are allocated coefficients at or near 0 . Many of these procedures have attracted much attention recently; see, for example, bridge procedure Frank and Friedman (1993), Lasso procedure introduced in order to interpretability of regression models such as LARS (Efron, 2004), LARS process makes available a quick execution of the Lasso solution.

Zou and Hastie (2005) proposed the elastic net procedure to obtain enhanced performance when there is multicollinearity event between variables. In 2006, another regularization procedure introduced by Zou (2006), this procedure is adaptive Lasso regression, authorizing different penalty parameters to different regression coefficients, he proved that his proposed procedure had the characteristics of Oracle mentioned in Fan and Li (2001) that Lasso does not have. Park and Casella (2008) explicated that the parameters of the Lasso procedure can be estimated by the Bayesian pattern. Similarly, from a Bayesian point of view, "Bayesian Lasso regression (Hans, 2009)", "Bayesian adaptive Lasso; iterative adaptive Lasso (Sun, Zou, and Ibrahim, 2009)", "Bayesian adaptive Lasso with non-convex penalization (Griffin and Brown, 2010)", "The Bayesian elastic net (Li and Lin, 2010)", "A Bayesian Lasso via reversible jump MCMC (Chen, Wang, and McKeown, 2011)", "The new Bayesian Lasso (Mallick and Yi, 2014)", "Bayesian
adaptive Lasso (Leng, Tran, and Nott, 2014)", and "Bayesian variable selection and estimation for group Lasso ( Xu and Ghosh, 2015)".

In this thesis, we proposed two Bayesian regularization procedures, Bayesian Lasso and Bayesian adaptive Lasso in Tobit regression.

## CHAPTER TWO

## 2. BAYESIAN LASSO TOBIT REGRESSION

### 2.1 Introduction:

The Lasso (least absolute shrinkage and selection operator) model is widely used as a regularization process for coefficient estimation in regression problems. Specifically, Tibshirani (1996) introduced Lasso method in order to interpretability of regression models, and get better prediction accuracy. The aim of the Lasso regression is to obtain a subset of the estimations that reduces the prediction error of the outcome variable, by imposing a constraint on model parameters that cause shrank the unimportant explanatory variables and reduced to zero. Efron (2004) presented an effective algorithm for calculating the Lasso estimates of $\beta_{j}$ via the LARS algorithm. The Lasso regression formulated as follows

$$
\begin{equation*}
\widehat{\boldsymbol{\beta}}_{\text {Lasso }}=\underset{\boldsymbol{\beta}}{\operatorname{argmin}}(\boldsymbol{y}-\boldsymbol{X} \boldsymbol{\beta})^{\prime}(\boldsymbol{y}-\boldsymbol{X} \boldsymbol{\beta})+\lambda \sum_{j=1}^{k}\left|\beta_{j}\right| \ldots \lambda \geq 0 \tag{2.1}
\end{equation*}
$$

where $\lambda$ is a positive penalty parameter.
Tibshirani (1996) and Park and Casella (2008) explicated that the parameters of the Lasso regression can be estimated by the Bayesian pattern. Then Lasso will be taken as posterior mode underneath independent Laplace distribution prior for the $\beta_{j}$. On the other hand, Bayesian Lasso results are superbly like regular Lasso results. Though, the Bayesian Lasso is very simple to execute, and auto generate interval estimates for coefficients, containing the error variances. Following Andrews and Mallows (1974), Park and Casella (2008) represented the prior distribution of $\boldsymbol{\beta}$ as follows

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$$
\begin{array}{r}
\pi\left(\boldsymbol{\beta} \mid \sigma^{2}, \lambda\right)=\prod_{j=1}^{k} \frac{\lambda}{2 \sqrt{\sigma^{2}}} \exp \left\{-\frac{\lambda\left|\beta_{j}\right|}{\sqrt{\sigma^{2}}}\right\}, \\
=\prod_{j=1}^{k} \int_{0}^{\infty} \frac{1}{\sqrt{2 \pi \sigma^{2} t_{j}}} \exp \left(-\frac{\beta_{j}{ }^{2}}{2 \sigma^{2} t_{j}}\right) \frac{\lambda^{2}}{2} \exp \left(-\frac{\lambda^{2}}{2} t_{j}\right) d t_{j} . \tag{2.2}
\end{array}
$$

Hans (2009) introduced a new aspect of other Bayesian remediation of Lasso regression, by using a new Gibbs sampler for Bayesian Lasso regression. Mallick and Yi (2014) proposed a new Bayesian Lasso by using scale mixture of uniform instead of scale mixture of normal distribution that used in Park and Casella (2008). The findings of Mallick and Yi (2014) in his research were very good and proved their efficiency from the previous Bayesian processes used. The good results notified in Mallick and Yi (2014) process encourage us to use the new Bayesian procedure in Tobit regression.
Recently, a new representation of the Laplace density given by Mallick and Yi (2014), this representation provided a different process of Lasso based model by using the scale mixture of a uniform representation of the Laplace density. This representation is written as follows:

$$
\begin{align*}
& \pi\left(\boldsymbol{\beta} \mid \sigma^{2}, \lambda\right)=\prod_{j=1}^{k} \frac{\lambda}{2 \sqrt{\sigma^{2}}} \exp \left\{-\frac{\lambda\left|\beta_{j}\right|}{\sqrt{\sigma^{2}}}\right\}, \\
= & \prod_{j=1}^{k} \frac{\lambda}{2 \sqrt{\sigma^{2}}} \int_{u_{j}>\frac{\left|\beta_{j}\right|}{\sqrt{\sigma^{2}}}} \lambda e^{-\lambda u_{j}} d u_{j} \tag{2.3}
\end{align*}
$$

They pointed out that the posterior distribution $\pi\left(\boldsymbol{\beta} \mid \sigma^{2}, \lambda\right)$ is similar to the main procedure of Park and Casella (2008), this formulation has gorgeous properties. In addition, Alhamzawi (2018) developed a new Gibbs sampler for Bayesian Lasso

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via mixture of truncated normal formulation with exponential mixture densities. In this thesis, following Mallick and Yi (2014), we used a new hierarchical representation of BLTR.

### 2.2 BLTR hierarchy model and prior distributions:

Mallick and Yi (2014) proposed Bayesian Lasso procedure as follows:

$$
\begin{equation*}
\frac{\lambda}{2} e^{-\lambda\left|\beta_{j}\right|}=\int_{w>\left|\beta_{j}\right|} \frac{1}{2 w} \frac{\lambda^{2}}{\Gamma(2)} w^{2-1} e^{-\lambda w} d w \ldots \lambda \geq 0 \tag{2.4}
\end{equation*}
$$

In this thesis, we adopted the above formula as follows:
Let $z_{j}=\lambda w_{j} \quad \Rightarrow d z_{j}=\lambda d w_{j}$ then

$$
\begin{gather*}
\frac{\lambda}{2} e^{-\lambda\left|\beta_{j}\right|}=\int_{z_{j}>\lambda\left|\beta_{j}\right|} \frac{\lambda}{2 z_{j}} \frac{\lambda^{2}}{\Gamma 2}\left(\frac{z_{j}}{\lambda}\right)^{2-1} e^{-z_{j}} \frac{1}{\lambda} d z_{j}, \\
=\int_{z_{j}>\lambda\left|\beta_{j}\right|} \frac{\lambda}{2} e^{-z_{j}} d z_{j} \ldots \lambda \geq 0 \tag{2.5}
\end{gather*}
$$

The hierarchical model of BLTR is

$$
\begin{gather*}
y_{i}=\left\{\begin{array}{lr}
y_{i}^{*} & y_{i}^{*}>0 \\
0 & \text { otherwise } \leq 0
\end{array}\right. \\
\boldsymbol{y}^{*} \mid \boldsymbol{X}, \boldsymbol{\beta}, \sigma^{2} \sim N\left(\boldsymbol{X} \boldsymbol{\beta}, \sigma^{2} I_{n}\right), \\
\beta_{j} \left\lvert\, \lambda \sim \operatorname{Uniform}\left(-\frac{1}{\lambda}, \frac{1}{\lambda}\right)\right.,  \tag{2.6}\\
z_{j} \sim \operatorname{Exp}(1),
\end{gather*}
$$

$$
\begin{aligned}
\sigma^{2} & \sim \operatorname{InvGamma}(a, b) \\
\lambda & \sim \operatorname{Gamma}(h, d)
\end{aligned}
$$

where $\boldsymbol{z}=\left(z_{1}, \cdots, z_{k}\right)$

### 2.3 Full conditional posterior distributions of BLTR:

The conditional distribution of $\boldsymbol{y}^{*}$ is follows:

$$
y_{i}^{*} \mid y_{i}, \boldsymbol{\beta} \sim\left\{\begin{array}{lc}
y_{i}, & \text { if } y_{i}^{*}>y^{0} \\
N\left(\boldsymbol{X} \boldsymbol{\beta}, \sigma^{2} I_{n}\right) I\left\{y_{i}^{*} \leq y^{0}\right\}, & \text { otherwise }
\end{array}\right\}
$$

where $y^{0}$ is a known censoring point.
Then the conditional posterior distribution of $\boldsymbol{\beta}$ as follows:

$$
\begin{gather*}
\pi\left(\boldsymbol{\beta} \mid \boldsymbol{y}^{*}, \boldsymbol{X}, \mathbf{z}, \sigma^{2}\right) \propto \pi\left(\boldsymbol{y}^{*} \mid \boldsymbol{X}, \boldsymbol{\beta}, \sigma^{2}\right) \pi(\boldsymbol{\beta} \mid \boldsymbol{z}), \\
\propto \exp \left\{-\frac{1}{2 \sigma^{2}}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{\left|\beta_{j}\right|<\frac{z_{j}}{\lambda}\right\}, \\
\propto \exp \left\{-\frac{1}{2 \sigma^{2}}\left(-2 \boldsymbol{y}^{* \prime} \boldsymbol{X} \boldsymbol{\beta}+\boldsymbol{\beta}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{\left|\beta_{j}\right|<\frac{z_{j}}{\lambda}\right\}, \\
\propto \exp \left\{-\frac{1}{2 \sigma^{2}}\left(-2 \widehat{\boldsymbol{\beta}}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{\beta}^{*}+\boldsymbol{\beta}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{-\frac{z_{j}}{\lambda}<\beta_{j}<\frac{z_{j}}{\lambda}\right\}, \\
\boldsymbol{\beta} \mid \boldsymbol{y}^{*}, \boldsymbol{X}, \mathbf{z} \sim N_{k}\left(\widehat{\boldsymbol{\beta}}_{O L S},\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \sigma^{2}\right) \prod_{j=1}^{k} I\left\{-\frac{z_{j}}{\lambda}<\beta_{j}<\frac{z_{j}}{\lambda}\right\} . \tag{2.7}
\end{gather*}
$$

The conditional posterior distribution of $\mathbf{z}$ as follows:

$$
\begin{aligned}
& \pi(\mathbf{z} \mid \boldsymbol{\beta}, \lambda) \propto \pi(\boldsymbol{\beta} \mid \mathbf{z}, \lambda) \pi(\mathbf{z}) \\
& \propto \prod_{j=1}^{k} e^{-z_{j}} I\left\{z_{j}>\lambda\left|\beta_{j}\right|\right\}
\end{aligned}
$$

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$$
\begin{equation*}
\mathbf{z} \sim \prod_{j=1}^{k} \text { Exponential(1) } I\left\{z_{j}>\lambda\left|\beta_{j}\right|\right\} \tag{2.8}
\end{equation*}
$$

The conditional posterior distribution of $\sigma^{2}$ as follows:

$$
\begin{gather*}
\pi\left(\sigma^{2} \mid \boldsymbol{y}^{*}, \boldsymbol{X}, \boldsymbol{\beta}\right) \propto \pi\left(\boldsymbol{y}^{*} \mid \boldsymbol{X}, \boldsymbol{\beta}, \sigma^{2}\right) \pi\left(\sigma^{2}\right), \\
\propto\left(\sigma^{2}\right)^{-\frac{n}{2}} \exp \left\{-\frac{1}{2 \sigma^{2}}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)\right\}\left(\sigma^{2}\right)^{-a-1} \exp \left\{-\frac{b}{\sigma^{2}}\right\}, \\
\sigma^{2} \mid \boldsymbol{y}^{*}, \boldsymbol{X}, \boldsymbol{\beta} \sim \operatorname{InvGamma}\left(\frac{n}{2}+a, \frac{1}{2}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)+b\right) . \tag{2.9}
\end{gather*}
$$

The conditional posterior distribution of $\lambda$ as follows:

$$
\begin{gather*}
\pi(\lambda \mid \boldsymbol{\beta}) \propto \pi(\boldsymbol{\beta} \mid \lambda) \pi(\lambda), \\
\propto \lambda^{k} \lambda^{h-1} e^{-\lambda d} \prod_{j^{\prime}=1}^{k} I\left\{\lambda<\frac{z_{j}}{\left|\beta_{j}\right|}\right\}, \\
\propto \lambda^{(k+h)-1} \exp \{-\lambda d\} \prod_{j^{\prime}=1}^{k} I\left\{\lambda<\frac{z_{j}}{\left|\beta_{j}\right|}\right\}, \\
\lambda \left\lvert\, \boldsymbol{\beta} \sim \operatorname{Gamma}((k+h), d) \prod_{j^{\prime}=1}^{k} I\left\{\lambda<\frac{z_{j}}{\left|\beta_{j}\right|}\right\}\right., \tag{2.10}
\end{gather*}
$$

where the $\widehat{\boldsymbol{\beta}}_{O L S}$ is ordinary least squares estimators, and $I($.$) denotes an indicator$ function.

### 2.4 BLTR computation:

In the beginning, we specify Gibbs samples for BLTR procedure by initiate with the initial valuations for parameters $\boldsymbol{\beta}, \boldsymbol{z}, \lambda$ and $\sigma^{2}$, then we carry out the algorithm as follows:

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Algorithm 1 (Sampling in BLTR model).

- Sampling $\boldsymbol{y}^{*}$ : We generate $\boldsymbol{y}^{*}$ latent variable from truncated normal distribution with mean $\boldsymbol{X} \boldsymbol{\beta}$ and variance $\sigma^{2} I_{n}$.
- Sampling z : We generate $z_{j}$ as follows $z_{j}=z_{j}{ }^{*}+\lambda\left|\beta_{j}\right|$, where $z_{j}{ }^{*}$ is an exponential distribution.
- Sampling $\boldsymbol{\beta}$ : We generate $\boldsymbol{\beta}$ coefficients from truncated normal distribution with $\left.\widehat{\boldsymbol{\beta}}_{o L S},\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \sigma^{2}\right)$.
- Sampling $\boldsymbol{\sigma}^{2}$ : We generate $\sigma^{2}$ from inverse gamma distribution with shape parameter $\frac{n}{2}+a$ and rate parameter

$$
\frac{1}{2}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)+b .
$$

- Sampling $\lambda$ : We generate $\lambda$ from truncated gamma distribution with shape parameter $k+h$ and rate parameter $d$.


### 2.5 BLTR with ridge parameter:

In practice, the above procedure performs very well. However, the above estimator of $\widehat{\boldsymbol{\beta}}_{\text {OLS }}$ is highly unsteady in the existence of multicollinearity. In addition, the matrix $\boldsymbol{X}^{\prime} \boldsymbol{X}$ is singular if explanatory variables $k$ is more than $n$. Gupta and Ibrahim (2007) have developed a process to deal with these situations. Specifically,

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they added a ridge parameter within $\boldsymbol{X}^{\prime} \boldsymbol{X}$ matrix. Following Gupta and Ibrahim (2007), we added the ridge parameter remedy actual challenges that may appear via multicollinearity and overfitting problems.

Now, referring to the equation (2.7) and adding ridge parameter $\vartheta$ to the equation, we will get

$$
\begin{gather*}
\exp \left\{-\frac{1}{2 \sigma^{2}}\left(-2 \boldsymbol{y}^{* \prime} \boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right)^{-\mathbf{1}}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right) \boldsymbol{\beta}\right.\right. \\
\left.\left.+\boldsymbol{\beta}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right) \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{\left|\beta_{j}\right|<\frac{z_{j}}{\lambda}\right\}, \\
\propto \exp \left\{-\frac{1}{2 \sigma^{2}}\left(-2 \boldsymbol{\beta}_{\boldsymbol{R}}{ }^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right) \boldsymbol{\beta}+\boldsymbol{\beta}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right) \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{\left|\beta_{j}\right|<\frac{z_{j}}{\lambda}\right\}, \\
\boldsymbol{\beta} \mid \boldsymbol{y}^{*}, \boldsymbol{X}, \mathbf{z} \sim N_{k}\left(\boldsymbol{\beta}_{\boldsymbol{R}},\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right)^{-1} \sigma^{2}\right) \prod_{j=1}^{k} I\left\{-\frac{z_{j}}{\lambda}<\beta_{j}<\frac{z_{j}}{\lambda}\right\} . \tag{2.11}
\end{gather*}
$$

where the $\boldsymbol{\beta}_{\boldsymbol{R}}$ is ridge estimators and $I($.$) denotes an indicator function.$

### 2.6 BLTR with ridge parameter computation:

We require Gibbs samples for BLTR procedure with ridge parameter by initiate with the initial valuations for parameters $\boldsymbol{\beta}, \mathbf{z}, \lambda$ and $\sigma^{2}$, then we carry out the algorithm as follows:

Algorithm 2 (Sampling in BLTR model with ridge parameter).

- Sampling $\boldsymbol{y}^{*}$ : We generate $\boldsymbol{y}^{*}$ latent variable from truncated normal distribution with mean $\boldsymbol{X} \boldsymbol{\beta}$ and variance $\sigma^{2} I_{n}$.
- Sampling $z:$ We generate the $z_{j}$ as follows $z_{j}=z_{j}{ }^{*}+\lambda\left|\beta_{j}\right|$, where $z_{j}{ }^{*}$ is an exponential distribution.
- Sampling $\boldsymbol{\beta}$ : We generate $\boldsymbol{\beta}$ coefficients from truncated normal with mean $\boldsymbol{\beta}_{\boldsymbol{R}}$ and variance covariance $\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right)^{-1} \sigma 2$.
- Sampling $\boldsymbol{\sigma}^{2}$ : We generate $\sigma^{2}$ from inverse gamma distribution with shape parameter $\frac{n}{2}+a$ and rate parameter

$$
\frac{1}{2}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)+b
$$

- Sampling $\lambda$ : We generate $\lambda$ from truncated gamma distribution with shape parameter $k+h$ and rate parameter $d$.


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## CHAPTER THREE

## 3. BAYESIAN ADAPTIVE LASSO TOBIT REGRESSION

### 3.1 Introduction:

A lot of work has been devoted to the development of diverse Bayesian organizational procedures for making a variable selection in linear models. One of these approaches is adaptive Lasso, as a regularization method, evades overfitting penalizing large coefficients. Also, it has the same advantage that Lasso, it can shrink some of the coefficients to exactly zero, giving subsequently a selection of attributes by the regularization. Zou (2006) proposed the adaptive Lasso, who upgraded the Lasso way proposed by Tibshirani (1996), the adaptive Lasso procedure permitting different penalty parameters to different regression coefficients. Zou (2006) proved that his proposed procedure had the characteristics of Oracle mentioned in Fan and Li (2001) that Lasso does not have. Specifically, Zou (2006) indicates that his proposed procedure adopts the correct form of nonzero coefficients with the probability that he tends to one. Park and Casella (2008) suggested the Lasso procedure based on a Bayesian point of sight. Likewise, Mallick and Yi (2014) suggested a new procedure known to be as new Bayesian Lasso regression for VS and coefficient estimation in linear regression. In general, the last procedure observed results display that the Mallick and Yi (2014) procedure applied well compares with other Bayesian and non-Bayesian regression procedures.

The good results reported in Mallick procedure motivate us to suggest a new Bayesian regression procedure. Subsequently, we suggested a Bayesian hierarchical for adaptive Lasso Tobit regression (BALTR), and proposed a new

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Gibbs sampler (GS) for BALTR, that is sets up on a theoretical derivation of the Laplace density.

It is well known, that the Lasso procedure gives biased estimates of considerable coefficients, so it might be below the required best level in terms of estimation risks. Zou (2006) evidenced that the Lasso selects the incorrect model with nonfade the probability, despite the sample size and how $\lambda$ is chosen. The event requires that coefficients not in the model aren't representable by coefficients in the real models. But this event is simply suffering because of the collinearity cases between the coefficients. On the opposite hand, that the Lasso process does not have Oracle properties. So, Zou (2006) suggested the adaptive Lasso technique which gives a consistent model for VS. Therefore, we consider BALTR approach in this thesis, the adaptive Lasso enjoys the Oracle properties by utilizing the adaptably weighted Lasso penalty parameter, and leads to a near minimax good estimators. Additionally, the adaptive Lasso technique needs to initials estimates of the regression coefficients, when a sample sizes is less than of the covariates number, which is mostly not available in the high dimensional data. The estimator of adaptive Lasso is given by

$$
\begin{equation*}
\widehat{\boldsymbol{\beta}}_{\text {Alasso }}=\underset{\boldsymbol{\beta}}{\operatorname{argmin}}(\boldsymbol{y}-\boldsymbol{X} \boldsymbol{\beta})^{\prime}(\boldsymbol{y}-\boldsymbol{X} \boldsymbol{\beta})+\sum_{j=1}^{k} \lambda_{j}\left|\beta_{j}\right| \ldots \lambda_{j} \geq 0, \tag{3.1}
\end{equation*}
$$

where varied penalty parameters are utilized for the regression coefficients. Confidently, for the not important explanatory variables, we must place larger penalty $\lambda_{j}$ on their matching coefficients.

We propose a BALTR procedure in this thesis for coefficients estimations and VS. We suggest a news practices of the adaptive Lasso form by using the scale

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mixtures of a uniform representation of the Laplace distribution. Following Mallick \& Yi (2014), the Laplace representation in equation (2.4) can adaptive as

$$
\frac{\lambda_{j}}{2} e^{-\lambda_{j}\left|\beta_{j}\right|}=\int_{w_{j}>\left|\beta_{j}\right|} \frac{1}{2 w_{j}} \frac{\lambda_{j}^{2}}{\Gamma 2} w_{j}^{2-1} e^{-\lambda_{j} w_{j}} d w_{j} \ldots \lambda_{j} \geq 0
$$

In this thesis, we modify the above formula as follows:
Let $z_{j}=\lambda_{j} w_{j} \quad \Rightarrow \quad d z_{j}=\lambda_{j} d w_{j} \quad$ then

$$
\begin{align*}
& \frac{\lambda_{j}}{2} e^{-\lambda_{j}\left|\beta_{j}\right|}=\frac{\lambda_{j}}{2} e^{-\left|\lambda_{j} \beta_{j}\right|}, \\
& =\int_{z_{j}>\left|\lambda_{j} \beta_{j}\right|} \frac{\lambda_{j}}{2 z_{j}} \frac{\lambda_{j}^{2}}{\Gamma 2}\left(\frac{z_{j}}{\lambda_{j}}\right)^{2-1} e^{-z_{j}} \frac{1}{\lambda_{j}} d z_{j}, \\
& =\int_{z_{j}>\left|\lambda_{j} \beta_{j}\right|} \frac{\lambda_{j}}{2} e^{-z_{j}} d z_{j} \ldots \lambda_{j} \geq 0 \tag{3.2}
\end{align*}
$$

In practices, this formula produces more tractable and efficient Gibbs Samples than the previous formula.

### 3.2 BALTR hierarchy model and Prior Distributions:

By using equation (1.1) and equation (3.2), the Bayesian hierarchical model can be formulated as follows:

$$
\begin{gather*}
y_{i}=\left\{\begin{array}{lr}
y_{i}^{*} & y_{i}^{*}>0 \\
0 & \text { otherwise } \leq 0
\end{array},\right. \\
\boldsymbol{y}^{*} \mid \boldsymbol{X}, \boldsymbol{\beta}, \sigma^{2} \sim N_{n}\left(\boldsymbol{X} \boldsymbol{\beta}, \sigma^{2} I_{n}\right), \\
\boldsymbol{\beta} \mid \lambda \sim \prod_{j=1}^{k} \text { Uniform }\left(-\frac{1}{\lambda_{j}}, \frac{1}{\lambda_{j}}\right),  \tag{3.3}\\
\mathbf{z} \sim \prod_{j=1}^{k} \text { Exponential(1), }
\end{gather*}
$$

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$$
\begin{gathered}
\sigma^{2} \sim \operatorname{InvGamma}(a, b), \\
\lambda_{j} \sim \operatorname{Gamma}(c, d)
\end{gathered}
$$

where $\mathbf{z}=\left(z_{1}, \cdots, z_{k}\right)$ and $\boldsymbol{\lambda}=\left(\lambda_{1}, \cdots, \lambda_{k}\right)$.

### 3.3 Full Conditional Posterior Distributions of BALTR:

Firstly, we can express the joint posterior distribution of all BALTR procedure parameters as follows

The distribution of $\boldsymbol{y}^{*}$ is follows:

$$
y_{i}^{*} \mid y_{i}, \boldsymbol{\beta} \sim\left\{\begin{array}{ll}
y_{i}, & \text { if } y_{i}^{*}>y^{0} \\
N\left(\boldsymbol{X} \boldsymbol{\beta}, \sigma^{2} I_{n}\right) I\left\{y_{i}^{*} \leq y^{0}\right\}, & \text { otherwise }
\end{array}\right\} .
$$

The conditional posterior distribution of $\boldsymbol{\beta}$ is follows:

$$
\begin{gather*}
\pi\left(\boldsymbol{\beta}, \mathbf{z}, \boldsymbol{\lambda}, \sigma^{2} \mid \boldsymbol{y}^{*}, \boldsymbol{X}\right) \propto \pi\left(\boldsymbol{y}^{*} \mid \boldsymbol{X}, \boldsymbol{\beta}, \sigma^{2}\right) \pi(\boldsymbol{\beta} \mid \boldsymbol{\lambda}), \\
\propto \exp \left\{-\frac{1}{2 \sigma^{2}}\left(\boldsymbol{y}^{*}-X \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{y}^{*}-X \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{\left|\beta_{j}\right|<\frac{z_{j}}{\lambda_{j}}\right\}, \\
\propto \exp \left\{-\frac{1}{2 \sigma^{2}}\left(-2 \boldsymbol{y}^{* \prime} \boldsymbol{X} \boldsymbol{B}+\boldsymbol{\beta}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{\left|\beta_{j}\right|<\frac{z_{j}}{\lambda_{j}}\right\}, \\
\propto \exp \left\{-\frac{1}{2 \sigma^{2}}\left(-2 \boldsymbol{y}^{* \prime} \boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-\mathbf{1}}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right) \boldsymbol{\beta}+\boldsymbol{\beta}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{\left|\beta_{j}\right|<\frac{z_{j}}{\lambda_{j}}\right\}, \\
\propto \exp \left\{-\frac{1}{2 \sigma^{2}}\left(-2 \widehat{\boldsymbol{\beta}}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{\beta}+\boldsymbol{\beta}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{-\frac{z_{j}}{\lambda_{j}}<\beta_{j}<\frac{z_{j}}{\lambda_{j}}\right\}, \\
\boldsymbol{\beta} \mid \boldsymbol{y}^{*}, \boldsymbol{X}, \boldsymbol{z}, \boldsymbol{\lambda} \sim N_{k}\left(\widehat{\boldsymbol{\beta}}_{o L S}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \sigma^{2}\right) \prod_{j=1}^{k} I\left\{-\frac{z_{j}}{\lambda_{j}}<\beta_{j}<\frac{z_{j}}{\lambda_{j}}\right\} . \tag{3.4}
\end{gather*}
$$

The conditional posterior distribution of $\mathbf{z}$ as follows:

$$
\begin{gathered}
\pi(\mathbf{z} \mid \boldsymbol{\beta}, \boldsymbol{\lambda}) \propto \pi(\boldsymbol{\beta} \mid \mathbf{z}, \lambda) \pi(\mathbf{z}) \\
\propto \pi(\mathbf{z}) I\left\{z_{j}>\left|\lambda_{j} \beta_{j}\right|\right\}, \\
\propto \\
\prod_{j=1}^{k} e^{-z_{j}} I\left\{z_{j}>\left|\lambda_{j} \beta_{j}\right|\right\},
\end{gathered}
$$

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$$
\begin{equation*}
\mathbf{z} \sim \prod_{j=1}^{k} \text { Exponential(1) } I\left\{z_{j}>\left|\lambda_{j} \beta_{j}\right|\right\} \tag{3.5}
\end{equation*}
$$

The conditional posterior distribution of $\sigma^{2}$ as follows:

$$
\begin{gather*}
\pi\left(\sigma^{2} \mid \boldsymbol{y}^{*}, \boldsymbol{X}, \boldsymbol{\beta}\right) \propto \pi\left(\boldsymbol{y}^{*} \mid \boldsymbol{X}, \boldsymbol{\beta}, \sigma^{2}\right) \pi\left(\sigma^{2}\right), \\
\propto\left(\sigma^{2}\right)^{-\frac{n}{2}} \exp \left\{-\frac{1}{2 \sigma^{2}}\left(y^{*}-X \beta\right)^{\prime}\left(y^{*}-X \beta\right)\right\}\left(\sigma^{2}\right)^{-a-1} \exp \left\{-\frac{b}{\sigma^{2}}\right\}, \\
\sigma^{2} \mid \boldsymbol{y}^{*}, \boldsymbol{X}, \boldsymbol{\beta} \sim \operatorname{InvGamma}\left(\frac{n}{2}+a, \frac{1}{2}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)+b\right) . \tag{3.6}
\end{gather*}
$$

The conditional posterior distribution of $\lambda$ as follows:

$$
\begin{gather*}
\pi\left(\lambda_{j} \mid \beta_{j}\right) \propto \pi\left(\beta_{j} \mid \lambda_{j}\right) \pi\left(\lambda_{j}\right), \\
\propto \lambda_{j} \pi\left(\lambda_{j}\right) I\left\{\lambda_{j}<\frac{z_{j}}{\left|\beta_{j}\right|}\right\}, \\
\propto \lambda_{j}^{(c+1)-1} \exp \left\{-d \lambda_{j}\right\} I\left\{\lambda_{j}<\frac{z_{j}}{\left|\beta_{j}\right|}\right\}, \\
\lambda_{j} \left\lvert\, \beta_{j} \sim \operatorname{Gamma}(c+1, d) I\left\{\lambda_{j}<\frac{z_{j}}{\left|\beta_{j}\right|}\right\}\right., \tag{3.7}
\end{gather*}
$$

where the $\widehat{\boldsymbol{\beta}}_{\text {OLS }}$ is ordinary least squares estimators and $I($.$) denotes an indicator$ function.

### 3.4 BALTR computation:

We specify Gibbs samples for BALTR procedure by initiate with the initial valuations for parameters $\boldsymbol{\beta}, \mathbf{z}, \boldsymbol{\lambda}$ and $\sigma^{2}$, then we carry out the algorithm as follows:

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Algorithm 3 (Sampling in BALTR model).

- Sampling $\boldsymbol{y}^{*}$ : We generate $\boldsymbol{y}^{*}$ latent variable from truncated normal distribution with mean $\boldsymbol{X} \boldsymbol{\beta}$ and variance $\sigma^{2} I_{n}$.
- Sampling z: We generate the $z_{j}$ as follows $z_{j}=z_{j}{ }^{*}+\left|\lambda_{j} \beta_{j}\right|$, where $z_{j}{ }^{*}$ is an exponential distribution.
- Sampling $\boldsymbol{\beta}$ : We generate $\boldsymbol{\beta}$ coefficients from truncated normal distribution with mean $\boldsymbol{\beta}_{\text {ols }}$ and variance covariance $\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \sigma^{2}$.
- Sampling $\boldsymbol{\sigma}^{2}$ : We generate the $\sigma^{2}$ from the inverse gamma distribution with shape parameter $\frac{n}{2}+a$ and rate parameter

$$
\frac{1}{2}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)+b .
$$

- Sampling $\lambda$ : We generate the $\lambda_{j}$ from truncated gamma distribution with shape parameter $c+1$ and rate parameter $d$.


### 3.5 BALTR with ridge parameter:

For the same reasons mentioned in Chapter 2, exactly in section 2.5, we adding a ridge parameter to remedy actual challenges that may appear with multicollinearity and overfitting problems. Then, referring to the equation (3.4) and add ridge parameter $\vartheta$ to the equation as follows:

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$$
\begin{gather*}
\exp \left\{-\frac{1}{2 \sigma^{2}}\left(-2 \boldsymbol{y}^{* \prime} \boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right)^{-1}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right) \boldsymbol{\beta}\right.\right. \\
\left.\left.+\boldsymbol{\beta}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right) \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{\left|\beta_{j}\right|<\frac{z_{j}}{\lambda_{j}}\right\}, \\
\propto \exp \left\{-\frac{1}{2 \sigma^{2}}\left(-2 \boldsymbol{\beta}_{\boldsymbol{R}}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right) \boldsymbol{\beta}+\boldsymbol{\beta}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right) \boldsymbol{\beta}\right)\right\} \prod_{j=1}^{k} I\left\{\left|\beta_{j}\right|<\frac{z_{j}}{\lambda_{j}}\right\}, \\
\boldsymbol{\beta} \mid \boldsymbol{y}^{*}, \boldsymbol{X}, \mathbf{z}, \boldsymbol{\lambda} \sim N_{k}\left(\boldsymbol{\beta}_{R},\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right)^{-1} \sigma^{2}\right) \prod_{j=1}^{k} I\left\{-\frac{z_{j}}{\lambda_{j}}<\beta_{j}<\frac{z_{j}}{\lambda_{j}}\right\}, \tag{3.8}
\end{gather*}
$$

where the $\boldsymbol{\beta}_{\boldsymbol{R}}$ is ridge estimators and $I($.$) denotes an indicator function.$

### 3.6 BALTR with ridge parameter computation:

We specify Gibbs samples for BALTR procedure with ridge parameter by initiate with the initial valuations for parameters $\boldsymbol{\beta}, \boldsymbol{z}, \boldsymbol{\lambda}$ and $\sigma^{2}$, then we carry out the algorithm as follows

Algorithm 4 (Sampling in BALTR model with ridge parameter).

- Sampling $\boldsymbol{y}^{*}$ : We generate the latent variable $\boldsymbol{y}^{*}$ from truncated normal distribution with mean $\boldsymbol{X} \boldsymbol{\beta}$ and variance $\sigma^{2} I_{n}$.
- Sampling z: We generate $\boldsymbol{z}$ as follows $z_{j}=z_{j}{ }^{*}+\left|\lambda_{j} \beta_{j}\right|$, where $z_{j}{ }^{*}$ is an exponential distribution.
- Sampling $\boldsymbol{\beta}$ : We generate $\boldsymbol{\beta}$ coefficients from truncated normal distribution with mean $\boldsymbol{\beta}_{\boldsymbol{R}}$ and variance covariance $\left(\boldsymbol{X}^{\prime} \boldsymbol{X}+\vartheta I_{k}\right)^{-1} \sigma^{2}$.

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- Sampling $\boldsymbol{\sigma}^{2}$ : We generate the $\sigma^{2}$ from the inverse gamma distribution with shape parameter $\frac{n}{2}+a$ and rate parameter

$$
\frac{1}{2}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{y}^{*}-\boldsymbol{X} \boldsymbol{\beta}\right)+b .
$$

- Sampling $\lambda_{\text {: }}$ We generate the $\lambda_{j}$ from truncated gamma distribution with shape parameter $c+1$ and rate parameter $d$.


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## CHAPTER FOUR

## 4. SIMULATION STUDY ANALYSIS

### 4.1 Introduction:

In this part of this Chapter, we test our proposed procedures and measure its performance compared to previous techniques for estimating parameters and VS in Tobit regression. This test is carried out by applying simulation examples to our procedures BALTR and BLTR, Tobit regression (Tr) by implementing the AER package (Kleiber et al., 2017), Bayesian Tobit regression method (Btr) by implementing the MCMCpack package (Martin et al., 2018), and the Bayesian Tobit Quantile regression method (Btqr) by using the Brq package (Alhamzawi, 2018). All these packages will be implemented in R language. For comparison, we draw 10,000 iterations of the Gibbs sampling, the first 1000 were ruled out as burn in. The procedures are evaluated based on the median of mean absolutes deviations MMAD). The formula of MMAD as follows

$$
\begin{equation*}
\text { MMAD }=\operatorname{median}\left(\text { mean }\left(\left|\boldsymbol{X} \widehat{\boldsymbol{\beta}}-\boldsymbol{X} \boldsymbol{\beta}^{\text {true }}\right|\right),\right. \tag{4.1}
\end{equation*}
$$

where the parameter $\widehat{\boldsymbol{\beta}}$ is a vector of estimated coefficients and the parameter $\boldsymbol{\beta}^{\text {true }}$ is a vector of true coefficients values in the simulation examples. In this chapter, we set $\mathrm{a}=\mathrm{b}=\mathrm{c}=\mathrm{d}=0.05, \vartheta=0.01$ and $\mathrm{Tau}=0.5$. For each simulation study, we run 200 simulations.

### 4.2 Independents and identically distributed (i.i.d) random errors:

Here, a clarification of what we will do in this simulation, that we will create independent variables from the multivariate normal distribution with parameters mean 0 , and three values of the variance $\sigma^{2}$.

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### 4.2.1 Simulation example 1:

In this simulations example, we create 7 independent variables with 100 observations, the pair wise correlation between each independent variable equalizes to $0.5^{|i-j|}$, and we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(1,0,1,0,1,0,1,0)^{\prime} .
$$

We simulated $y_{i}^{*}$ as follows:

$$
y_{i}^{*}=1+x_{2 i}+x_{4 i}+x_{6 i}+\varepsilon_{i}
$$

where $\varepsilon_{i} \sim \operatorname{Normal}\left(0, \sigma^{2}\right)$, and $\sigma^{2} \in\{1,4,9\}$.
We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.98827 | 0.98864 | 0.99785 | 0.96099 | 0.97584 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{0}$ | 0.00038 | 0.00045 | 0.00002 | 0.00145 | 0.00296 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{1}$ | 1.01733 | 1.01547 | 1.01471 | 1.03469 | 1.02866 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.00748 | -0.00737 | -0.00842 | -0.00566 | -0.00396 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{1}$ | 1.00599 | 1.00435 | 1.00140 | 1.02812 | 1.03061 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.00089 | -0.00054 | -0.00036 | -0.00301 | 0.00045 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{1}$ | 1.00329 | 1.00104 | 0.99984 | 1.02516 | 1.02201 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | -0.00801 | -0.00840 | -0.00916 | -0.00666 | -0.01113 |

Table 1: The coefficients estimates of Simulation example 1, when $\varepsilon_{i} \sim N(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | $\mathbf{T r}$ | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.96165 | 0.96346 | 0.98341 | 0.90094 | 0.92477 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{0}$ | -0.03419 | -0.03484 | -0.03525 | -0.03771 | -0.04608 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{1}$ | 1.03859 | 1.03449 | 1.03971 | 1.07396 | 1.08750 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.01906 | -0.01769 | -0.01797 | -0.02327 | -0.04456 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{1}$ | 0.99276 | 0.98515 | 1.00533 | 1.04831 | 1.07056 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.00555 | -0.00538 | -0.00443 | 0.00100 | -0.01794 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{1}$ | 0.96883 | 0.96457 | 0.97656 | 1.00677 | 1.00723 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | -0.00152 | -0.00026 | 0.00109 | -0.00239 | -0.01064 |

Table 2: The coefficients estimates of Simulation example 1, when $\varepsilon_{i} \sim \mathrm{~N}(0,4)$

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| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=1$ | 0.93230 | 0.93821 | 0.98741 | 0.85266 | 0.92306 |
| $\boldsymbol{\beta}_{\mathbf{1}}=0$ | -0.00241 | -0.00409 | -0.00274 | 0.00304 | 0.00642 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{1}$ | 0.90639 | 0.89763 | 0.96096 | 1.00688 | 0.97875 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.06056 | 0.06073 | 0.06894 | 0.06871 | 0.08918 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{1}$ | 0.92676 | 0.91765 | 0.95287 | 1.00207 | 0.97170 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.00396 | -0.00296 | -0.00268 | -0.00263 | 0.01202 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{1}$ | 0.93320 | 0.92347 | 0.97901 | 1.02463 | 1.01493 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | 0.02254 | 0.01934 | 0.01915 | 0.01989 | 0.00235 |

Table 3: The coefficients estimates of Simulation example 1, when $\varepsilon_{i} \sim N(0,9)$

| Procedure | $\boldsymbol{\sigma}^{\mathbf{2}}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.253714 | 0.066260 |
| BLTR |  | 0.254578 | 0.068390 |
| Tr | 1 | 0.255161 | 0.069849 |
| BTr |  | 0.264513 | 0.075860 |
| BTqr |  | 0.282732 | 0.077842 |
| BALTR |  | 0.486562 | 0.142146 |
| BLTR |  | 0.487090 | 0.142711 |
| Tr | 4 | 0.492903 | 0.149641 |
| BTr |  | 0.508624 | 0.168405 |
| BTqr |  | 0.559407 | 0.166772 |
| BALTR |  | 0.688334 | 0.197845 |
| BLTR |  | 0.699088 | 0.196353 |
| Tr | 9 | 0.711708 | 0.209395 |
| BTr |  | 0.735739 | 0.231249 |
| BTqr |  | 0.789161 | 0.230088 |

Table 4: The MMADs and SDs results of Simulation example 1

### 4.2.2 Simulation example 2:

This simulation example is same as example above except we create 8 independent variables, and we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(1,2,1,0,0,2,0,0,0)^{\prime} .
$$

We simulated $y_{i}^{*}$ as follows:

$$
y_{i}^{*}=1+2 x_{1 i}+x_{2 i}+2 x_{5 i}+\varepsilon_{i}
$$

where $\varepsilon_{i} \sim \operatorname{Normal}\left(0, \sigma^{2}\right)$, and $\sigma^{2} \in\{1,4,9\}$.
We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.97159 | 0.97221 | 0.98196 | 0.94891 | 0.93512 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{2}$ | 2.00872 | 2.00722 | 2.00367 | 2.03296 | 2.00367 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{1}$ | 1.00763 | 1.00670 | 1.00807 | 1.01861 | 1.00807 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.03387 | 0.03542 | 0.03594 | 0.03729 | 0.05146 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.02673 | -0.02681 | -0.02934 | -0.02641 | -0.02389 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{2}$ | 2.03684 | 2.03427 | 2.03763 | 2.04875 | 2.05431 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.01184 | -0.01180 | -0.01395 | -0.00831 | -0.01093 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | 0.01131 | 0.01112 | 0.01176 | 0.01293 | 0.01731 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | 0.02385 | 0.02455 | 0.02422 | 0.02653 | 0.03331 |

Table 5: The coefficients estimates of Simulation example 2, when $\varepsilon_{i} \sim \mathrm{~N}(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | $\mathbf{T r}$ | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.97095 | 0.97731 | 1.00273 | 0.89674 | 0.90440 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{2}$ | 1.99212 | 1.98133 | 1.98334 | 2.04186 | 2.02277 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{1}$ | 0.99698 | 0.99874 | 1.00515 | 1.03967 | 1.03717 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.01277 | 0.01409 | 0.01603 | 0.00550 | -0.01092 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.00038 | -0.00033 | -0.00220 | 0.00672 | -0.01011 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{2}$ | 2.01144 | 1.99696 | 2.00244 | 2.06962 | 2.08351 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.01746 | -0.01740 | -0.01891 | -0.02984 | -0.03428 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | 0.00332 | 0.00659 | 0.00527 | 0.00489 | 0.02098 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | -0.01538 | -0.01637 | -0.01637 | -0.01705 | -0.03639 |
| Table 6: The coefficients | estimates of Simulation example 2, when | $\varepsilon_{i} \sim \mathrm{~N}(0,4)$ |  |  |  |

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| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.88552 | 0.91542 | 0.94838 | 0.73714 | 0.79963 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{2}$ | 2.09478 | 2.06696 | 2.09071 | 2.19900 | 2.16909 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{1}$ | 0.95556 | 0.95517 | 1.00633 | 1.07622 | 1.09604 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.01773 | -0.02413 | -0.01887 | -0.00588 | -0.01590 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.06045 | 0.06462 | 0.06589 | 0.06675 | 0.07159 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{2}$ | 2.02103 | 1.98286 | 2.02437 | 2.14770 | 2.15143 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.04312 | -0.04821 | -0.04970 | -0.05432 | -0.04958 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | 0.01631 | 0.01681 | 0.02267 | 0.03698 | 0.01310 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | -0.02775 | -0.02589 | -0.02533 | -0.02832 | -0.03070 |

Table 7: The coefficients estimates of Simulation example 2, when $\varepsilon_{i} \sim N(0,9)$

| Procedure | $\boldsymbol{\sigma}^{\mathbf{2}}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.2867665 | 0.0784412 |
| BLTR |  | 0.2878924 | 0.0794854 |
| Tr | 1 | 0.2886266 | 0.0804479 |
| BTr |  | 0.3030122 | 0.0875418 |
| BTqr |  | 0.3292688 | 0.0884608 |
| BALTR |  | 0.5291207 | 0.1342116 |
| BLTR |  | 0.5317522 | 0.1358630 |
| Tr | 4 | 0.5358101 | 0.1419345 |
| BTr |  | 0.5736709 | 0.1478548 |
| BTqr |  | 0.6248725 | 0.1717885 |
| BALTR |  | 0.8161338 | 0.2344180 |
| BLTR |  | 0.8247406 | 0.2504589 |
| Tr | 9 | 0.8639433 | 0.2594731 |
| BTr |  | 0.9450992 | 0.3328603 |
| BTqr |  | 0.9945814 | 0.3460455 |

Table 8: The MMADs and SDs results of Simulation example 2

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### 4.2.3 Simulation example 3:

In this simulation example, we create 7 independent variables with 200 observations, the pair wise correlation between each independent variable equalizes to $0.5^{|i-j|}$, and we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(1,6,0,0,0,0,0,0)^{\prime} .
$$

We simulated $y_{i}^{*}$ as follows:

$$
y_{i}^{*}=1+6 x_{1 i}+\varepsilon_{i}
$$

where $\varepsilon_{i} \sim \operatorname{Normal}\left(0, \sigma^{2}\right)$, and $\sigma^{2} \in\{1,4,9\}$.
We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.97368 | 0.97753 | 0.98879 | 0.94602 | 0.94129 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{6}$ | 6.01734 | 6.00915 | 6.00311 | 6.04569 | 6.06105 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | 0.01687 | 0.02028 | 0.02032 | 0.01908 | 0.00891 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.02981 | -0.03250 | -0.03228 | -0.03437 | -0.03492 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.01732 | 0.01819 | 0.01768 | 0.01843 | 0.01383 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.00262 | -0.00358 | -0.00503 | 0.00219 | 0.00320 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.00378 | -0.00401 | -0.00218 | -0.00925 | -0.00812 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | -0.00518 | -0.00384 | -0.00430 | -0.00595 | -0.01012 |

Table 9: The coefficients estimates of Simulation example 3, when $\varepsilon_{i} \sim \mathrm{~N}(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.94907 | 0.96559 | 1.00646 | 0.88484 | 0.89730 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{6}$ | 6.02860 | 5.99982 | 5.97664 | 6.10380 | 6.09037 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | -0.02884 | -0.03165 | -0.03466 | -0.02816 | -0.01705 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.02693 | 0.02488 | 0.02954 | 0.01865 | 0.01067 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.02435 | -0.02439 | -0.02528 | -0.03082 | -0.00979 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.00439 | -0.00282 | -0.00963 | 0.01587 | 0.01298 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | 0.03007 | 0.03157 | 0.04076 | 0.02071 | -0.00122 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | -0.00213 | 0.00071 | 0.00041 | 0.00368 | 0.02046 |

Table 10: The coefficients estimates of Simulation example 3, when $\varepsilon_{i} \sim \mathrm{~N}(0,4)$

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| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :--- | :--- | :--- | :--- | :--- | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.85252 | 0.90898 | 0.97288 | 0.78279 | 0.78323 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{6}$ | 6.12307 | 6.04103 | 6.01833 | 6.21566 | 6.25580 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | -0.00169 | -0.01736 | -0.02162 | 0.00461 | 0.02084 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.00479 | -0.00091 | 0.00215 | -0.02989 | -0.04074 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.01931 | 0.02467 | 0.02528 | 0.03211 | 0.03718 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.03964 | -0.03964 | -0.03971 | -0.06806 | -0.08469 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.01256 | -0.00415 | -0.00234 | -0.01975 | -0.01429 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | -0.00448 | -0.006959 | -0.01159 | 0.00913 | 0.01829 |

Table 11: The coefficients estimates of Simulation example 3, when $\varepsilon_{i} \sim N(0,9)$

| Procedure | $\boldsymbol{\sigma}^{\mathbf{2}}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.3106147 | 0.1013127 |
| BLTR |  | 0.3115898 | 0.1060711 |
| Tr | 1 | 0.3121467 | 0.1046592 |
| BTr |  | 0.3161041 | 0.1115924 |
| BTqr |  | 0.3446810 | 0.1168242 |
| BALTR |  | 0.5711975 | 0.1695946 |
| BLTR |  | 0.5864465 | 0.1737943 |
| Tr |  | 0.5941101 | 0.1866304 |
| BTr |  | 0.6330689 | 0.1966508 |
| BTqr |  | 0.6741430 | 0.2176665 |
| BALTR |  | 0.8190953 | 0.2743333 |
| BLTR |  | 0.8360951 | 0.2539165 |
| Tr | 9 | 0.8664098 | 0.2966426 |
| BTr |  | 0.8928808 | 0.3108317 |
| BTqr |  | 0.9693136 | 0.3371386 |

Table 12: The MMADs and SDs results of Simulation example 3

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### 4.2.4 Simulation example 4:

In this simulation example, we create 8 independent variables with 100 observations, the pair wise correlation between each independent variable equalizes to 0,9 , and we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(1,4,0,0,0,0,0,0,0)^{\prime} .
$$

We simulated $y_{i}^{*}$ as follows:

$$
y_{i}^{*}=1+4 x_{1 i}+\varepsilon_{i}
$$

where $\varepsilon_{i} \sim \operatorname{Normal}\left(0, \sigma^{2}\right)$, and $\sigma^{2} \in\{1,4,9\}$.
We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.98066 | 0.98114 | 0.99732 | 0.94336 | 0.94509 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{4}$ | 4.01580 | 4.01280 | 4.00121 | 4.05204 | 4.05518 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | -0.02369 | -0.02443 | -0.02401 | -0.02597 | -0.02490 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.00661 | 0.00656 | 0.00627 | 0.00755 | -0.00942 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.01306 | -0.01326 | -0.01122 | -0.01811 | -0.01485 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.01593 | -0.01743 | -0.01530 | -0.02417 | -0.02233 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.01972 | -0.02033 | -0.01952 | -0.02484 | -0.02248 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | 0.00007 | -0.00030 | -0.00002 | -0.00108 | -0.00336 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | 0.00155 | 0.00184 | 0.00259 | 0.00056 | 0.00530 |

Table 13: The coefficients estimates of Simulation example 4, when $\varepsilon_{i} \sim \mathrm{~N}(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | $\mathbf{T r}$ | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.93806 | 0.94796 | 0.98354 | 0.85672 | 0.87234 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{4}$ | 4.00038 | 3.97771 | 3.95982 | 4.09213 | 4.09190 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | -0.05298 | -0.05676 | -0.05471 | -0.06522 | -0.05747 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.01241 | 0.01078 | 0.01139 | 0.01108 | 0.01751 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.01391 | 0.01499 | 0.01537 | 0.01834 | 0.01579 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.00205 | -0.00121 | -0.00191 | -0.00161 | -0.00616 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | 0.00512 | 0.00353 | 0.00019 | 0.01596 | 0.02037 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | -0.00527 | -0.00625 | -0.00654 | -0.00443 | 0.00298 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | 0.02382 | 0.02719 | 0.02781 | 0.02752 | 0.01539 |

Table 14: The coefficients estimates of Simulation example 4 , when $\varepsilon_{i} \sim \mathrm{~N}(0,4)$

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| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.85857 | 0.87405 | 0.93708 | 0.76538 | 0.79680 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{4}$ | 4.06267 | 4.03328 | 4.02374 | 4.15795 | 4.14522 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | 0.01158 | 0.01511 | 0.01580 | 0.02550 | 0.02188 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.04653 | -0.04888 | -0.05147 | -0.05095 | -0.05048 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.00739 | -0.00989 | -0.01354 | 0.00265 | 0.01444 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.02513 | -0.02520 | -0.02375 | -0.03634 | -0.03140 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | 0.02400 | 0.01936 | 0.01766 | 0.01341 | 0.01714 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | 0.01162 | 0.01649 | 0.01981 | 0.01195 | 0.00986 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | 0.01130 | 0.00759 | 0.00732 | 0.01839 | 0.01591 |

Table 15: The coefficients estimates of Simulation example 4 , when $\varepsilon_{i} \sim N(0,9)$

| Procedure | $\boldsymbol{\sigma}^{\mathbf{2}}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.3175153 | 0.0878509 |
| BLTR |  | 0.3188315 | 0.0883490 |
| Tr | 1 | 0.3241813 | 0.0892745 |
| BTr |  | 0.3317360 | 0.0943799 |
| BTqr |  | 0.3483748 | 0.0999571 |
| BALTR |  | 0.5533796 | 0.1576824 |
| BLTR |  | 0.5586609 | 0.1638874 |
| Tr | 4 | 0.5673092 | 0.1745200 |
| BTr |  | 0.5902533 | 0.1929422 |
| BTqr |  | 0.6342843 | 0.2009979 |
| BALTR |  | 0.7782545 | 0.2106083 |
| BLTR |  | 0.7823382 | 0.2187003 |
| Tr | 9 | 0.8064242 | 0.2196771 |
| BTr |  | 0.8462888 | 0.2480293 |
| BTqr |  | 0.8727480 | 0.2616631 |

Table 16: The MMADs and SDs results of Simulation example 4

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### 4.2.5 Simulation example 5:

In this example, we set the same number of observations and same true regression coefficients in the example above. But, the pair wise correlation between $x_{i}$ and $x_{j}$ is high correlation and it is equal to 0,75 .

We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.96334 | 0.97432 | 0.98914 | 0.93030 | 0.93054 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{4}$ | 3.99911 | 3.97485 | 3.96787 | 4.03959 | 4.04445 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | 0.02810 | 0.02907 | 0.02915 | 0.03780 | 0.05102 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.05722 | -0.05931 | -0.05809 | -0.07588 | -0.09464 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.03286 | 0.03630 | 0.03240 | 0.05007 | 0.05885 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | 0.02766 | 0.02966 | 0.03094 | 0.02647 | 0.02646 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.03771 | -0.04115 | -0.03994 | -0.04496 | -0.05025 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | 0.00514 | 0.00745 | 0.00778 | 0.01035 | 0.02153 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | 0.01061 | 0.01078 | 0.01007 | 0.01590 | 0.01057 |

Table 17: The coefficients estimates of Simulation example 5 , when $\varepsilon_{i} \sim \mathrm{~N}(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.90221 | 0.92680 | 0.98491 | 0.85950 | 0.87261 |
| $\boldsymbol{\beta}_{\mathbf{1}}=4$ | 4.09041 | 4.05841 | 4.03304 | 4.14416 | 4.14184 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | -0.02764 | -0.03752 | -0.03607 | -0.04203 | -0.05109 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.03041 | -0.02766 | -0.03004 | -0.03646 | -0.04094 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.08249 | 0.07324 | 0.06840 | 0.10042 | 0.13265 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.02687 | -0.03145 | -0.02989 | -0.04422 | -0.06207 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | 0.01350 | 0.00990 | 0.00329 | 0.01418 | 0.02799 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | -0.03645 | -0.03800 | -0.03699 | -0.05141 | -0.06235 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | 0.04680 | 0.04654 | 0.04803 | 0.05217 | 0.06563 |

Table 18: The coefficients estimates of Simulation example 5 , when $\varepsilon_{i} \sim \mathrm{~N}(0,4)$

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| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.73119 | 0.78657 | 0.94885 | 0.75659 | 0.80464 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{4}$ | 4.12586 | 4.03465 | 3.99195 | 4.14338 | 4.15168 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | 0.02199 | 0.02505 | 0.04213 | 0.04481 | 0.00129 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.02119 | -0.04096 | -0.07182 | -0.04829 | -0.00941 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.02292 | 0.04250 | 0.06801 | 0.04011 | 0.02100 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | 0.05144 | 0.04283 | 0.02239 | 0.04867 | 0.07637 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.04245 | -0.05081 | -0.03979 | -0.05118 | -0.06790 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | 0.01408 | 0.00877 | -0.00874 | 0.00103 | 0.03011 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | 0.73119 | 0.78657 | 0.94885 | 0.75659 | 0.80464 |

Table 19: The coefficients estimates of Simulation example 5 , when $\varepsilon_{i} \sim N(0,9)$

| Procedure | $\boldsymbol{\sigma}^{\mathbf{2}}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.3143854 | 0.1002000 |
| BLTR |  | 0.3157433 | 0.1004268 |
| Tr | 1 | 0.3249725 | 0.1007086 |
| BTr |  | 0.3270238 | 0.1140092 |
| BTqr |  | 0.3693706 | 0.1202663 |
| BALTR |  | 0.5635968 | 0.1528850 |
| BLTR |  | 0.5690248 | 0.1624616 |
| Tr | 4 | 0.5784414 | 0.1919185 |
| BTr |  | 0.5923137 | 0.1807643 |
| BTqr |  | 0.6501139 | 0.1794833 |
| BALTR |  | 0.7290041 | 0.2281853 |
| BLTR |  | 0.7558415 | 0.2599720 |
| Tr | 9 | 0.8092581 | 0.2846500 |
| BTr |  | 0.8406544 | 0.2806326 |
| BTqr |  | 0.8931200 | 0.2883510 |

Table 20: The MMADs and SDs results of Simulation example 5

## Bayesian adaptive Lasso Tobit regression with a practical application

### 4.2.6 Simulation example 6:

In this simulation example, we create 7 independent variables with 200 observations, the pair wise correlation between each independent variable equalize to $0.5^{|i-j|}$, and we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(0, \underbrace{0.7, \ldots, 0.7}_{7})^{\prime} .
$$

We simulated $y_{i}^{*}$ as follows:

$$
y_{i}^{*}=0.7 x_{1 i}+0.7 x_{2 i}+0.7 x_{3 i}+0.7 x_{4 i}+0.7 x_{5 i}+0.7 x_{6 i}+0.7 x_{7 i}+\varepsilon_{i}
$$

where $\varepsilon_{i} \sim \operatorname{Normal}\left(0, \sigma^{2}\right)$, and $\sigma^{2} \in\{1,4,9\}$.
We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{0}$ | -0.00121 | -0.00423 | -0.00533 | -0.08591 | -0.06556 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{0 . 7}$ | 0.70947 | 0.71037 | 0.71166 | 0.73317 | 0.73406 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0 . 7}$ | 0.69885 | 0.69889 | 0.69910 | 0.70385 | 0.69077 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0 . 7}$ | 0.70073 | 0.70289 | 0.70702 | 0.72777 | 0.73125 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0 . 7}$ | 0.67094 | 0.67292 | 0.67990 | 0.69661 | 0.69749 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0 . 7}$ | 0.68911 | 0.68964 | 0.69058 | 0.69096 | 0.68514 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0 . 7}$ | 0.69695 | 0.69789 | 0.69921 | 0.72360 | 0.71674 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0 . 7}$ | 0.69993 | 0.70086 | 0.70014 | 0.72937 | 0.72692 |

Table 21: The coefficients estimates of Simulation example 6 , when $\varepsilon_{i} \sim \mathrm{~N}(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{0}$ | 0.01359 | -0.00959 | -0.02789 | -0.20080 | -0.15736 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{0 . 7}$ | 0.67988 | 0.68716 | 0.70428 | 0.72475 | 0.71989 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0 . 7}$ | 0.68443 | 0.69440 | 0.71776 | 0.74273 | 0.73490 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0 . 7}$ | 0.68594 | 0.70291 | 0.73325 | 0.78796 | 0.79404 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0 . 7}$ | 0.70081 | 0.67994 | 0.70662 | 0.72362 | 0.73400 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0 . 7}$ | 0.69904 | 0.68332 | 0.71282 | 0.76138 | 0.73504 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0 . 7}$ | 0.68678 | 0.69480 | 0.70902 | 0.73962 | 0.76310 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0 . 7}$ | 0.69172 | 0.67046 | 0.68789 | 0.71432 | 0.69523 |

Table 22: The coefficients estimates of Simulation example 6 , when $\varepsilon_{i} \sim \mathrm{~N}(0,4)$

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| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{0}$ | -0.05573 | -0.03550 | -0.07786 | -0.35636 | -0.28588 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{0 . 7}$ | 0.67484 | 0.66341 | 0.70466 | 0.76623 | 0.77236 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0 . 7}$ | 0.66696 | 0.64567 | 0.74590 | 0.81375 | 0.83822 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0 . 7}$ | 0.69203 | 0.68537 | 0.69142 | 0.72902 | 0.69549 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0 . 7}$ | 0.70936 | 0.61233 | 0.69836 | 0.75535 | 0.76538 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0 . 7}$ | 0.63479 | 0.61751 | 0.69721 | 0.75672 | 0.76575 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0 . 7}$ | 0.74763 | 0.73993 | 0.77888 | 0.83389 | 0.84087 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0 . 7}$ | 0.68780 | 0.66230 | 0.65789 | 0.69270 | 0.66976 |

Table 23: The coefficients estimates of Simulation example 6 , when $\varepsilon_{i} \sim N(0,9)$

| Procedure | $\boldsymbol{\sigma}^{\mathbf{2}}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.276327 | 0.104663 |
| BLTR |  | 0.277788 | 0.105090 |
| Tr | 1 | 0.280375 | 0.106778 |
| BTr |  | 0.286062 | 0.127102 |
| BTqr |  | 0.305961 | 0.126867 |
| BALTR |  | 0.545705 | 0.137516 |
| BLTR | 4 | 0.545787 | 0.141699 |
| Tr |  | 0.549043 | 0.154127 |
| BTr |  | 0.612324 | 0.198907 |
| BTqr |  | 0.626475 | 0.200574 |
| BALTR |  | 0.785711 | 0.230850 |
| BLTR |  | 0.805738 | 0.253614 |
| Tr |  | 0.814186 | 0.285252 |
| BTr |  | 0.906358 | 0.377037 |
| BTqr |  | 0.946205 | 0.386729 |

Table 24: The MMADs and SDs results of Simulation example 6

## Bayesian adaptive Lasso Tobit regression with a practical application

### 4.2.7 Simulation example 7:

This example considers a difficult case model. We create 4 independent variables with 100 observations, and the pair wise correlation between each independent variable is low correlation, it is equalized to -0.25 , and we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(0,6.8,6.8,6.8,0)^{\prime} .
$$

And we simulated $y_{i}^{*}$ as follows:

$$
y_{i}^{*}=6.8 x_{1 i}+6.8 x_{2 i}+6.8 x_{3 i}+\varepsilon_{i}
$$

where $\varepsilon_{i} \sim \operatorname{Normal}\left(0, \sigma^{2}\right)$, and $\sigma^{2} \in\{1,4,9\}$.
We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{0}$ | -0.03204 | -0.02874 | -0.02564 | -0.04972 | -0.04884 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{6 . 8}$ | 6.81289 | 6.80855 | 6.80866 | 6.82615 | 6.82673 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{6 . 8}$ | 6.82236 | 6.81757 | 6.81833 | 6.83434 | 6.82800 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{6 . 8}$ | 6.80231 | 6.79864 | 6.79951 | 6.81096 | 6.79943 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.00738 | -0.00849 | -0.00822 | -0.00876 | -0.01579 |

Table 25: The coefficients estimates of Simulation example 7, when $\varepsilon_{i} \sim N(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{0}$ | -0.01848 | -0.01769 | -0.00053 | -0.07119 | -0.05421 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{6 . 8}$ | 6.80706 | 6.80504 | 6.79841 | 6.83788 | 6.83524 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{6 . 8}$ | 6.78025 | 6.77714 | 6.77373 | 6.80896 | 6.79998 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{6 . 8}$ | 6.81374 | 6.81031 | 6.80598 | 6.84394 | 6.84213 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.01473 | -0.01726 | -0.01741 | -0.01320 | -0.01883 |

Table 26: The coefficients estimates of Simulation example 7, when $\varepsilon_{i} \sim N(0,4)$

Bayesian adaptive Lasso Tobit regression with a practical application

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{0}$ | -0.05187 | -0.05787 | -0.00290 | -0.20772 | -0.22551 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{6 . 8}$ | 6.82950 | 6.82827 | 6.80091 | 6.94322 | 6.95459 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{6 . 8}$ | 6.88990 | 6.88623 | 6.86843 | 6.99837 | 7.01069 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{6 . 8}$ | 6.82117 | 6.81366 | 6.79564 | 6.93702 | 6.98893 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.03453 | 0.03309 | 0.03350 | 0.04149 | 0.04776 |

Table 27: The coefficients estimates of Simulation example 7, when $\varepsilon_{i} \sim \mathrm{~N}(0,9)$

| Procedure | $\boldsymbol{\sigma}^{\mathbf{2}}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.2715830 | 0.1158086 |
| BLTR |  | 0.2739781 | 0.1161730 |
| Tr | 1 | 0.2748512 | 0.1167151 |
| BTr |  | 0.2755876 | 0.1208232 |
| BTqr |  | 0.2970783 | 0.1276834 |
| BALTR |  | 0.4730141 | 0.2025605 |
| BLTR |  | 0.4736110 | 0.2042301 |
| Tr |  | 0.4852631 | 0.2043655 |
| BTr |  | 0.4895753 | 0.2118048 |
| BTqr |  | 0.5720289 | 0.2340398 |
| BALTR |  | 0.7991411 | 0.3320651 |
| BLTR |  | 0.8110890 | 0.3479748 |
| Tr | 9 | 0.8323682 | 0.3412223 |
| BTr |  | 0.8268126 | 0.4119798 |
| BTqr |  | 0.9511592 | 0.4644230 |

Table 28: The MMADs and SDs results of Simulation example 7

## Bayesian adaptive Lasso Tobit regression with a practical application

### 4.2.8 Simulation example 8:

This simulation example is same in the example above except the pair wise correlation between each independent variable is very low correlation, it is equalized to 0.95 , and we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(0,5.5,5.5,5.5,0)^{\prime} .
$$

We simulated $y_{i}^{*}$ as follows:

$$
y_{i}^{*}=5.5 x_{1 i}+5.5 x_{2 i}+5.5 x_{3 i}+\varepsilon_{i}
$$

where $\varepsilon_{i} \sim \operatorname{Normal}\left(0, \sigma^{2}\right)$, and $\sigma^{2} \in\{1,4,9\}$.
We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{0}$ | 0.00060 | 0.00606 | 0.01219 | -0.02171 | -0.02990 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{5 . 5}$ | 5.49903 | 5.49370 | 5.49235 | 5.51362 | 5.51767 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{5 . 5}$ | 5.49752 | 5.49176 | 5.49292 | 5.50951 | 5.50678 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{5 . 5}$ | 5.51334 | 5.50702 | 5.50574 | 5.53024 | 5.53255 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.00655 | -0.00587 | -0.00761 | -0.00458 | -0.00813 |

Table 29: The coefficients estimates of Simulation example 8 , when $\varepsilon_{i} \sim N(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{0}$ | -0.02741 | -0.02886 | -0.05559 | -0.09647 | -0.09765 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{5 . 5}$ | 5.53919 | 5.53667 | 5.52496 | 5.59940 | 5.60046 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{5 . 5}$ | 5.52721 | 5.52524 | 5.50943 | 5.58874 | 5.59006 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{5 . 5}$ | 5.54451 | 5.54064 | 5.53180 | 5.60197 | 5.62056 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.00502 | 0.00462 | 0.00431 | 0.01049 | 0.00578 |

Table 30: The coefficients estimates of Simulation example 8 , when $\varepsilon_{i} \sim \mathrm{~N}(0,4)$

Bayesian adaptive Lasso Tobit regression with a practical application

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{0}$ | -0.12842 | -0.14020 | -0.18551 | -0.28450 | -0.25737 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{5 . 5}$ | 5.53337 | 5.53558 | 5.50877 | 5.64924 | 5.64082 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{5 . 5}$ | 5.50742 | 5.50453 | 5.48611 | 5.62610 | 5.64194 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{5 . 5}$ | 5.57582 | 5.57051 | 5.56494 | 5.67917 | 5.67718 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.03505 | -0.04467 | -0.04179 | -0.03981 | -0.01707 |

Table 31: The coefficients estimates of Simulation example 8 , when $\varepsilon_{i} \sim N(0,9)$

| Procedure | $\sigma^{2}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.2693833 | 0.1276641 |
| BLTR |  | 0.2701359 | 0.1276692 |
| Tr | 1 | 0.2737591 | 0.1278145 |
| BTr |  | 0.2809201 | 0.1340808 |
| BTqr |  | 0.3205587 | 0.1549083 |
| BALTR |  | 0.4916656 | 0.2144122 |
| BLTR |  | 0.4948648 | 0.2147106 |
| Tr | 4 | 0.4962678 | 0.2168003 |
| BTr |  | 0.5145276 | 0.2295402 |
| BTqr |  | 0.5344612 | 0.2361655 |
| BALTR |  | 0.6875267 | 0.3454354 |
| BLTR |  | 0.7362656 | 0.3522602 |
| Tr | 9 | 0.7448768 | 0.3553119 |
| BTr |  | 0.7762767 | 0.4178073 |
| BTqr |  | 0.7977359 | 0.4015878 |

Table 32: The MMADs and SDs results of Simulation example 8

## Bayesian adaptive Lasso Tobit regression with a practical application

### 4.2.9 Simulation example 9:

In this simulation example, we create 7 independent variables with 200 observations, and without intercept. The pair wise correlation between each independent variable equalize to $0.8^{|i-j|}$, and we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(1,0,0,1,0,0,1)^{\prime} .
$$

We simulated $y_{i}^{*}$ as follows:

$$
y_{i}^{*}=x_{1 i}+x_{4 i}+x_{7 i}+{ }^{\prime} \varepsilon_{i}
$$

where $\varepsilon_{i} \sim \operatorname{Normal}\left(0, \sigma^{2}\right)$, and $\sigma^{2} \in\{1,4,9\}$.
We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{1}$ | 0.99602 | 0.99472 | 0.99891 | 0.99938 | 1.00005 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | 0.02253 | 0.02361 | 0.02502 | 0.02872 | 0.02909 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.01936 | -0.02096 | -0.02302 | -0.01557 | -0.01819 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{1}$ | 0.98914 | 0.98748 | 0.98879 | 0.99998 | 1.01144 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | 0.00151 | 0.00218 | 0.00401 | 0.00070 | -0.00791 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | 0.00593 | 0.00778 | 0.00648 | 0.01289 | 0.01664 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{1}$ | 1.02899 | 1.02624 | 1.02538 | 1.05374 | 1.07164 |

Table 33: The coefficients estimates of Simulation example 9 , when $\varepsilon_{i} \sim \mathrm{~N}(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{1}$ | 1.00121 | 0.99423 | 1.00942 | 1.05071 | 1.06561 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | -0.01434 | -0.02126 | -0.01914 | -0.03293 | -0.03984 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | -0.00154 | -0.00022 | -0.00004 | -0.01048 | -0.01597 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{1}$ | 1.04370 | 1.03332 | 1.05055 | 1.10838 | 1.11395 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.02595 | -0.02849 | -0.02941 | -0.03784 | -0.02168 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | 0.02130 | 0.02220 | 0.01712 | 0.04521 | 0.00745 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{1}$ | 0.98648 | 0.98243 | 0.99409 | 1.00535 | 1.03446 |

Table 34: The coefficients estimates of Simulation example 9 , when $\varepsilon_{i} \sim N(0,4)$

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| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | $\mathbf{T r}$ | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{1}$ | 0.87722 | 0.87473 | 0.93722 | 0.93620 | 0.96776 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | 0.02059 | 0.02356 | 0.01815 | 0.02717 | 0.04077 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.03436 | 0.03484 | 0.04302 | 0.02835 | 0.02563 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{1}$ | 0.99151 | 0.97907 | 1.03864 | 1.08294 | 1.06385 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.02858 | -0.03023 | -0.03350 | -0.00132 | -0.01357 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.00635 | -0.01027 | -0.01450 | -0.03378 | -0.05047 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{1}$ | 1.00904 | 0.99530 | 1.05497 | 1.09108 | 1.10440 |

Table 35: The coefficients estimates of Simulation example 9 , when $\varepsilon_{i} \sim \mathrm{~N}(0,9)$

| Procedure | $\boldsymbol{\sigma}^{\mathbf{2}}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.2637977 | 0.0629574 |
| BLTR |  | 0.2645657 | 0.0630926 |
| Tr | 1 | 0.2661152 | 0.0641458 |
| BTr |  | 0.2690778 | 0.0672531 |
| BTqr |  | 0.3022255 | 0.0756868 |
| BALTR |  | 0.4451257 | 0.1621673 |
| BLTR |  | 0.4584184 | 0.1585630 |
| Tr |  | 0.4645096 | 0.1603979 |
| BTr |  | 0.4939741 | 0.1682316 |
| BTqr |  | 0.5428853 | 0.1769871 |
| BALTR |  | 0.6663666 | 0.1890329 |
| BLTR |  | 0.6716854 | 0.1890237 |
| Tr | 9 | 0.7004311 | 0.1977441 |
| BTr |  | 0.7115157 | 0.2022168 |
| BTqr |  | 0.7552406 | 0.2121890 |

Table 36: The MMADs and SDs results of Simulation example 9

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### 4.2.10 Simulation example 10:

This simulation example is same as example 9 except we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(2, \underbrace{0, \ldots, 0}_{6})^{\prime} \text {. }
$$

We simulated $y_{i}^{*}$ as follows:

$$
y_{i}^{*}=2 x_{1 i}+\varepsilon_{i}
$$

where $\varepsilon_{i} \sim \operatorname{Normal}\left(0, \sigma^{2}\right)$, and $\sigma^{2} \in\{1,4,9\}$.
We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{2}$ | 2.02453 | 2.02054 | 2.02216 | 2.03512 | 2.03164 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | 0.01362 | 0.01412 | 0.01344 | 0.01859 | 0.01118 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.00231 | 0.00285 | 0.00208 | 0.00654 | 0.00891 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.01615 | -0.01740 | -0.01611 | -0.02272 | -0.01397 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | 0.01777 | 0.01868 | 0.01845 | 0.02269 | 0.01890 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | 0.00883 | 0.00852 | 0.00901 | 0.00715 | 0.00495 |
| $\boldsymbol{\beta}_{\boldsymbol{7}}=\mathbf{0}$ | -0.00492 | -0.00466 | -0.00480 | -0.00474 | -0.00445 |

Table 37: The coefficients estimates of Simulation example 10 , when $\varepsilon_{i} \sim N(0,1)$

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{2}$ | 2.03589 | 2.01806 | 2.02225 | 2.09623 | 2.09136 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | -0.02655 | -0.02897 | -0.01920 | -0.06953 | -0.07637 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.01203 | 0.01314 | 0.00604 | 0.03564 | 0.03165 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.00093 | 0.00088 | 0.00063 | -0.00408 | -0.00881 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.00516 | -0.00285 | 0.00208 | -0.02818 | -0.01613 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | 0.00599 | 0.00667 | 0.00192 | 0.03046 | 0.02646 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | -0.03617 | -0.03757 | -0.04135 | -0.04638 | -0.04298 |

Table 38: The coefficients estimates of Simulation example 10 , when $\varepsilon_{i} \sim N(0,4)$

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| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{2}$ | 2.03086 | 1.98035 | 2.03613 | 2.12114 | 2.11584 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{0}$ | -0.00503 | -0.00731 | -0.01374 | -0.00790 | -0.01854 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.04881 | 0.04794 | 0.06198 | 0.05704 | 0.06209 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | 0.01883 | 0.01793 | 0.01211 | 0.06594 | 0.05424 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.01938 | -0.02196 | -0.02338 | -0.04635 | -0.03894 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | -0.00672 | -0.00744 | -0.00609 | -0.01412 | -0.00675 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | 0.00185 | -0.00638 | -0.00801 | -0.00229 | -0.00272 |

Table 39: The coefficients estimates of Simulation example 10 , when $\varepsilon_{i} \sim N(0,9)$

| Procedure | $\boldsymbol{\sigma}^{\mathbf{2}}$ | MMAD | SD |
| :---: | :---: | :---: | :---: |
| BALTR |  | 0.2425656 | 0.0606486 |
| BLTR |  | 0.2432271 | 0.0698898 |
| Tr | 1 | 0.2444597 | 0.0700119 |
| BTr |  | 0.2493422 | 0.0699531 |
| BTqr |  | 0.2732725 | 0.0735678 |
| BALTR |  | 0.4527618 | 0.1528419 |
| BLTR |  | 0.4556374 | 0.1539392 |
| Tr |  | 0.4613127 | 0.1539059 |
| BTr |  | 0.4755329 | 0.1625885 |
| BTqr |  | 0.5232845 | 0.1674268 |
| BALTR |  | 0.6200592 | 0.2003216 |
| BLTR |  | 0.6468788 | 0.2013237 |
| Tr | 9 | 0.7054764 | 0.2016802 |
| BTr |  | 0.7411863 | 0.2152123 |
| BTqr |  | 0.7909137 | 0.2284264 |

Table 40: The MMADs and SDs results of Simulation example 10

### 4.3 Non-i.i.d (Heterogeneous)random errors:

### 4.3.1 Simulation example 11:

In this simulation example, we created 100 observations, and 8 independent variables, 5 of these variables are represented as standard normal noise variables, and we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(1,2,1,2,0,0,0,0,0)^{\prime}
$$

We simulated $y_{i}^{*}$ as follows:

$$
\begin{gathered}
y_{i}^{*}=x_{i}^{\prime} \boldsymbol{\beta}+\left(1+x_{3 i}\right) \varepsilon_{i} \\
\text { where } \varepsilon_{i} \sim \operatorname{Normal}(0,1), \\
x_{1 i} \sim \operatorname{Normal}(0,1), x_{3 i} \sim \operatorname{Uniforms}(0,1), \\
x_{2 i}=x_{1 i}+x_{3 i}+z_{i}, z_{i} \sim \operatorname{Normal}(0,1)
\end{gathered}
$$

We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}=\mathbf{1}$ | 0.96936 | 0.96770 | 0.98601 | 0.96044 | 0.97442 |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{2}$ | 2.01515 | 2.01446 | 2.00962 | 2.02357 | 2.02289 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{1}$ | 0.99955 | 1.00096 | 0.99772 | 1.00197 | 0.99635 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{2}$ | 2.00402 | 1.98195 | 2.01909 | 2.02554 | 2.03448 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.00316 | -0.00300 | -0.00252 | -0.00489 | 0.00180 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | -0.01780 | -0.01785 | -0.01846 | -0.01910 | -0.02701 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{0}$ | 0.00675 | 0.00713 | 0.00685 | 0.00907 | 0.01659 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{0}$ | -0.01106 | -0.01131 | -0.01095 | -0.01031 | -0.00753 |
| $\boldsymbol{\beta}_{\mathbf{8}}=\mathbf{0}$ | 0.00066 | 0.00075 | 0.00121 | -0.00144 | 0.00883 |

Table 41: The coefficients estimates of Simulation example 11

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| Procedure | MMAD | SD |
| :---: | :---: | :---: |
| BALTR | 0.2488675 | 0.0673076 |
| BLTR | 0.2489086 | 0.0676727 |
| Tr | 0.2498349 | 0.0679520 |
| BTr | 0.2498877 | 0.0689287 |
| BTqr | 0.2718577 | 0.0777695 |

Table 42: The MMADs and SDs results of Simulation example 11

### 4.3.2 Simulation example 12:

This simulation example is same as example 11, except the number of independent variables is 7 , and without intercept, 4 variables are represented as standards normal noise variables. we set the true regression coefficients as follows:

$$
\boldsymbol{\beta}^{\text {true }}=(1,1,0,0,0,1,1)^{\prime}
$$

We list the results of regression coefficients estimates as tables below

| $\boldsymbol{\beta}^{\text {true }}$ | BALTR | BLTR | Tr | Btr | Btqr |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{1}}=\mathbf{1}$ | 0.97645 | 0.97437 | 0.98484 | 0.99867 | 1.02606 |
| $\boldsymbol{\beta}_{\mathbf{2}}=\mathbf{1}$ | 0.98797 | 0.98689 | 0.98858 | 1.00582 | 1.00308 |
| $\boldsymbol{\beta}_{\mathbf{3}}=\mathbf{0}$ | 0.07754 | 0.07911 | 0.09580 | -0.00931 | -0.05584 |
| $\boldsymbol{\beta}_{\mathbf{4}}=\mathbf{0}$ | -0.02608 | -0.02539 | -0.02589 | -0.02436 | -0.03266 |
| $\boldsymbol{\beta}_{\mathbf{5}}=\mathbf{0}$ | 0.01822 | 0.02086 | 0.02213 | 0.02496 | 0.01569 |
| $\boldsymbol{\beta}_{\mathbf{6}}=\mathbf{1}$ | 0.98689 | 0.98565 | 0.98829 | 0.99837 | 1.02980 |
| $\boldsymbol{\beta}_{\mathbf{7}}=\mathbf{1}$ | 1.01277 | 1.01076 | 1.01569 | 1.02484 | 1.03444 |

Table 43: The coefficients estimates of Simulation example 12

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| Procedure | MMAD | SD |
| :---: | :---: | :---: |
| BALTR | 0.3876545 | 0.1058635 |
| BLTR | 0.3880013 | 0.1059328 |
| Tr | 0.3898011 | 0.1064951 |
| BTr | 0.3975563 | 0.1119146 |
| BTqr | 0.4086063 | 0.1165248 |

Table 44: The MMADs and SDs results of Simulation example 12

From all tables of the previous examples, it can be observed that the proposed methods (BLTR and BALTR) generally perform better than the other methods ( Tr , Btr, and Btqr) used in the comparisons. The MMADs results of BALTR approach were relatively less than these results of the other procedures and gives the best MMADs and SD most of the times. This indicates the quality of the performance of the BALTR procedure in terms of coefficient estimation and VS.

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## CHAPTER FIVE

## 5. PRACTICAL APPLICATION

### 5.1 Introduction:

In this part of application chapter, and after we have demonstrated the merit of our proposed methods in the simulation study, we applied our proposed methods to the real data and then analyze the results statistically. The identification and detection of the causes about increasing the rate wheat production are one of the priorities of agricultural economist researchers. So, the determination of the real factors to increase wheat crop production among several factors that will help us to predict the rate of increase wheat production in the future. Hence the importance of our new proposed methods, which attempt to identify some variables and to show how strong their impact on the rate of increase in wheat production. We make our methods BALTR and BLTR within the three processes in wheat production data for comparison in terms of accurate prediction and variable selection. The data used in this chapter is taken from the National program for the development of wheat cultivation in Iraq; Qadisiyah governorate board (2017). The wheat production data includes 11 variables within 584 observations, these variables are sorting as follows in table 45 . The response variable in this dataset represents the relative increase in wheat yield per dunum, note that each dunum is equal to $2500 \mathrm{~m}^{2}$. R code is available upon request.

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### 5.2 The Independent variables:

- Urea fertilizer (U): The urea fertilizer is a simple fertilizer that supplies the major essential element nitrogen, and the crops need it in larger quantities than any other nutrient.
- Date of sowing (Ds): The date of cultivation of wheat seeds in the field.
- Quantity of sowing seeds (Qs): The quantity of wheat seeds in the field, and this amount is measured in kilograms per dunum.
- Laser field leveling technique (LT): This method is a smoothing procedure and leveling the farm ground. This method offers the potential for water savings.
- Compound fertilizer (NPK): NPK fertilizer is a complex fertilizer containing principally of the three fundamentals nutrients necessary for healthy plants growth (Nitrogen, Phosphorus and Potassium).
- Seed sowing machine technique (SMT): A sowing seed machine is a device that sows the seeds for crops in the soil, then cover the seeds to a nominated typical rate depth.
- Planting successive (SC): Successive planting is a way to extend corps harvest by staggering planting of crops, or planting varieties with staggered maturing dates. In this real dataset, the other corps which planting before sowing wheat seeds is Mung bean corp.
- Herbicide for weed (H): This process contains chemical applications. top control the growth of weeds types.
- High Potassium fertilizer (K): High Potassium is essential for crops health and there must be an adequate supply in the soils to maintain goods growth.


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- Micro-Elements fertilizer (ME): Mineral elements that are needed by crops in only trace amounts are known as micro-elements. This fertilizer which helps the growth of crops, such as iron, magnesium, potassium, and manganese.

| symbol | Variables description | Rank | Rank description |
| :---: | :---: | :---: | :---: |
| Y | The outcome variable | Percentage increase of wheat product |  |
| U | Urea fertilizer | Numeral | Quantity in kilogram |
| Ds | Date of sowing | 1 | Ideal |
|  |  | 2 | Early |
|  |  | 3 | Late |
| Qs | Quantity of sowing | Numeral | Quantity in kilogram |
| LT | Laser field leveling | 1 | Unused |
|  |  | 2 | Used |
| NPK | Compound fertilizer | Numeral | Quantity in kilogram |
| SMT | Sowing seeds machine | 1 | Unused |
|  |  | 2 | Used |
| SC | Planting successive | 1 | Planting |
|  | (Mung bean crop) | 2 | Not planting |
| H | Herbicide for weeds | Numeral | Quantity in milliliter |
| K | High Potassium | Numeral | Quantity in kilogram |
| ME | Micro-Elements | Numeral | Quantity int gram |

Table 45: The top 11 worthy variables

### 5.3 Real data results:

|  | BALTR | BLTR | Tr | Btr | Btqr |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $\boldsymbol{\beta}_{\mathbf{0}}$ | -0.0433838 | -0.0431762 | -0.084922 | -0.081976 | -1.2196515 |
| L.C I | -0.3578263 | -0.3604089 | -0.8722770 | -0.898573 | -1.8071276 |
| U.C I | 0.2323458 | 0.2673627 | 0.7024328 | 0.719634 | -0.4907951 |

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| U | 0.0211009 | 0.0213583 | 0.020928 | 0.020974 | 0.0243195 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L.C I | 0.0199047 | 0.0200037 | 0.0137744 | 0.013798 | 0.0176873 |
| U.C I | 0.0228502 | 0.0236142 | 0.0280822 | 0.028236 | 0.0307460 |
| Ds | -0.6671660 | -0.6763215 | -0.663651 | -0.665663 | -0.6545110 |
| L.C I | -0.7316255 | -0.7574811 | -0.7864428 | -0.790510 | -0.8024576 |
| U.C I | -0.6207167 | -0.6239916 | -0.5408589 | -0.546217 | -0.5029025 |
| Qs | -0.0218912 | -0.0220591 | -0.021788 | -0.021790 | -0.0057674 |
| L.C I | -0.0242680 | -0.0247427 | -0.0347353 | -0.034747 | -0.0177361 |
| U.C I | -0.0199373 | -0.0200504 | -0.0088414 | -0.008437 | 0.0032729 |
| LT | 1.3392113 | 1.2890701 | 1.357168 | 1.357630 | 1.4284952 |
| L.C I | 1.0704020 | 0.9941205 | 0.6807916 | 0.657868 | 0.4566205 |
| U.C I | 1.6029090 | 1.5630652 | 2.0335436 | 2.035161 | 2.3610716 |
| NPK | 0.0049840 | 0.0050224 | 0.004908 | 0.004920 | -0.0052290 |
| L.C I | 0.0033343 | 0.0033702 | -0.0075619 | -0.007545 | -0.0164622 |
| U.C I | 0.0069746 | 0.0071492 | 0.0173782 | 0.017452 | 0.0068326 |
| SMT | -0.0936879 | -0.1100872 | -0.142634 | -0.145098 | 0.2445190 |
| L.C I | -0.3627955 | -0.3842552 | -0.8377516 | -0.839958 | -0.6438307 |
| U.C I | 0.1158550 | 0.1310164 | 0.5524826 | 0.558794 | 1.2208572 |
| SC | 0.9282265 | 0.9198140 | 0.932829 | 0.930684 | 1.0000151 |
| L.C I | 0.8565598 | 0.8406293 | 0.6111322 | 0.600929 | 0.6683828 |
| U.C I | 0.9953362 | 0.9880197 | 1.2545265 | 1.258660 | 1.3113546 |
| H | 0.0043298 | 0.0043892 | 0.004315 | 0.004323 | 0.0051035 |
| L.C I | 0.0038758 | 0.0039010 | 0.0027357 | 0.002712 | 0.0037272 |
| U.C I | 0.0048939 | 0.0050331 | 0.0058946 | 0.005972 | 0.0064843 |
| K | 0.0327570 | 0.0328492 | 0.032676 | 0.032692 | 0.0246412 |
| L.C I | 0.0321197 | 0.0321597 | 0.0254615 | 0.025595 | 0.0139049 |
| U.C I | 0.0335991 | 0.0338707 | 0.0398907 | 0.039990 | 0.0360497 |
| ME | 0.0062279 | 0.0062152 | 0.006228 | 0.006250 | 0.0075853 |
| L.C I | 0.0060113 | 0.0059725 | 0.0045106 | 0.004517 | 0.0046838 |
| U.C I | 0.0063928 | 0.0063932 | 0.0079452 | 0.007948 | 0.0101096 |

Table 46 - Coefficients estimation and Credible intervals CIs (25\%, 95\%)

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In table 46, the results showed the coefficients estimation and credible intervals (low credible interval L.CI and upper credible interval U.CI). The credible interval results of the proposed techniques BLTR and BALTR are narrower than $\mathrm{Tr}, \mathrm{BTr}$, BTqr methods, and our proposed methods are including all the estimations of other methods. At the same time, the results described above have shown that the proposed method BALTR is the best technique of all other techniques used.


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Figure 1- Histograms of BLTR coefficients estimation








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Figure 2- Trace plots of BLTR coefficients estimation



Figure 3- Autocorrelations of BLTR coefficients estimation









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Figure 4- Histograms of BALTR coefficients estimation


## Bayesian adaptive Lasso Tobit regression with a practical application



Figure 5- Trace plots of BALTR coefficients estimation










Figure 6- Autocorrelations of BALTR coefficients estimation

The BLTR and BALTR coefficients estimation are based on posteriors samples of 10,000 recurrences.

In figures 1 and 4, which illustrates the histograms of BLTR and BALTR covariates, these histograms displayed that the conditional posteriors of the two methods are stationary for its underlying truncated normal distribution. In figures 2 and 5, showed the trace plots of BLTR and BALTR covariates, these plots show a reasonably good approximation, and the noise has significantly deviated and the chain has reached stability and the center remains relatively constant. This means that the chain is fully mixed and convergent. At last, from figures 3 and 6 , the plots showed the autocorrelations of BLTR and BALTR coefficients, the 10 covariates in these data are highly correlated, and these MCMCs chains in BLTR process were practically well.

## CHAPTER SIX

## 6. CONCLUSION \$ RECOMMENDATION

### 6.1 Conclusion:

This thesis has presented new techniques for model selection of Tobit regression from Bayesian framework, where we suggested BLTR, and BALTR procedures to estimates the coefficients with VS. The proposed procedures depend on the scale mixture uniform as prior distribution. We developed a new Bayesian hierarchical model for BLTR and BALTR procedures. Furthermore, we have provided the Gibbs samples for these procedures. The extension of our procedures has been included in our thesis, where the ridge parameter is added within the variance covariance matrix to prevent the singularity in case of multicollinearity and overfitting problems. We demonstrated the advantages of the new procedures in both simulations and analysis of real data in chapter four. The results showed that our procedures performed well in terms of VS and parameter estimation. In particular, the BALTR technique is absolutely the best of all the procedures mentioned above. Through the conclusions of this thesis, statisticians are assisted by the presence of BALTR technique in statistics, using this new technique to ensure accurate and useful results for the correct prediction.

### 6.2 Recommendations for future research:

The BLTR and BALTR procedures in this thesis will provide statistical researchers with promising hope, to introduce and extend new procedures for coefficients estimation and VS in the Tobit regression. There are many other probable extensions, such as, using the Bayesian group Lasso in Tobit regression, Bayesian

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elastic net in Tobit regression, Bayesian Bridge and group Bridge in Tobit regression.

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## الخلاصة

ان اجراء اختيار المتغيرات تثير إلى نوع المشاكل التي يحاول فيها المرء تحديد المجموعة الجزئية المثلى للمتغيرات ذات الصلة في النموذج ، والتي يمكن استخدامها للحصول على تعديلات دقيقة على نتائج متغير استجابة معين. في كثير من الأحيان ، عندما يكون عدد المتغيرات كبيرًا جدًا ، يصعب تحديد المتغيرات الهامة والمؤثرة في متغير الاستجابة. لهذا السبب ، اعتبرت اجراء اختيار التتغيرات مهمة جدا في تحليل البيانات. تعد طرق التتظيم من افضل الطرق التي أثبتت فعاليتها في التعامل مع الييانات عالية الأبعاد ، وفي اللنوات اللسابقة ، بذل الباحثون الإحصائيون جهودًا كبيرة في تطوير طرق التتظيم لحل مشاكل اختيار المتغيرات. فهذه الطرق تسهل تلقائياً عملية اختيار المتغيرات من خلال تعيين معاملات معيّنة إلى الصفر وتقليص المتبقي ، وتققيم تققيرات مفيدة حتى وان كان النموذج يحتوي على عدد كبير من متغيرات عالية الارتباط. بالرغم من تطوٌر طرق التنظيم في السنوات الأخيرة ، إلا أنه لا يز ال بالإمكان تحسين هذه الطرق. في هذه الرسالة ، اقترحنا طريقتان جديدتان لاختيار النموذج في انحدار توبت ، طريقة انحدار توبت لاسو البيزي وطريقة انحدار توبت لاسو التكيفي البيزي. تمتلكا الطريقتان ميزات كثيرة والتي اعطت افضل نقدير مع اختيار التنغيرات المهمة. وعلى وجه التحديد ، قدمنا نموذجًا هرمياً جديداً مع عينات جبس جديدة لكل طريقة.

ثم وسعنا الطريقتان المقترحتان عن طريق إضافة معلمة الحرف (Ridge) داخل مصفوفة التباين لتجنب حالة التفرد في مشكلة التعدد الخطي أو في حالة عدد المتغيرات أكبر من عدد من المثـاهدات. وتم إجراء مقارنة مع الطرق السابقة الأخرى من خلال تطبيق أمثلة المحاكاة واستخدام بيانات حققية. ومن الجدير بالذكر أن النتائج التي تم الحصول عليها واعدة ومشجعة ، والتي اعطت نتائج أفضل مقارنة بالطرق السابقة.

قَا لُو اسْبُحَحَنَكَ

سورة البقرة الآية (32)


> وزارة التعليم العالي والبحث العليي الادادارة والا قتصاد
انحدار توبت لاسو التكيفي البيزي

رسالة مقدمة
إلى بجلس كلية الإدارة والا قتصاد - جامعة القادسية وهي جزء من متطلبات نيل درجة الماجستير في علوم الإحصاء

من الطالب
حيدر كاظم عباس الهلالي
إشراف

الأستاذ الدكتور رحيم جبار المزاوي

